

ECTRI TG Safety Meeting
30 November 2020



Assessing the impact of personalized feedback on driving and riding behavior through a smartphone application



George Yannis, Armira Kontaxi, Apostolos Ziakopoulos

Department of Transportation Planning and Engineering,
National Technical University of Athens



Petros Fortsakis
OSeven Telematics

Introduction

- Accurate **monitoring of driver behavior** has scientific and technical requirements
- The Internet of Things (IoT) constantly offers new **opportunities and features** to monitor and analyze driver behavior through:
 - Wide use of smartphones and social media
 - Effective data collection and handling
 - Big Data Analysis



The BeSmart project

➤ Project partners:

- National Technical University of Athens, Department of Transportation Planning and Engineering www.nrso.ntua.gr
- OSeven Telematics www.oseven.io

➤ Duration of the project:

- 36 months (July 2018 – July 2021)

➤ Operational Program:

- "Competitiveness, Entrepreneurship and Innovation" (EPAnEK) of the National Strategic Reference Framework (NSRF)

BESMART



European Union
European Regional
Development Fund



ΕΡΑΝΕΚ 2014-2020
OPERATIONAL PROGRAMME
COMPETITIVENESS • ENTREPRENEURSHIP • INNOVATION

The BeSmart Objectives

➤ The objectives of the project:

- Development of an **innovative and seamless** Internet of Things **application**
- **Assessment and improvement of behavior** and safety of all drivers (car drivers, powered two-wheelers, cyclists, professional drivers) along multi-modal trips
- Organization and exploitation of a **naturalistic driving experiment** of 200 drivers for 12 months



Research Scope

- Identification of **the critical driving parameters that affect speeding** behavior using data from:
 - Smartphone devices
 - Naturalistic driving experiment
- Investigation of **the impact of driver feedback** on driving behavior as expressed by the exceedance of speed limits



The BeSmart driving experiment

- The experiment consists of **6 different phases** differing in the type of feedback provided to drivers
- The present study refers to the first two phases (car drivers – PTW riders):
 - **Phase 1 - no feedback** to drivers - 12 weeks duration
 - **Phase 2 - personalized feedback** in means of a trip list and a scorecard regarding drivers' behavior - 10 weeks duration
- A total of **26,619 trips** from a sample of 147 car drivers and **3,853 trips** from 20 motorcyclists



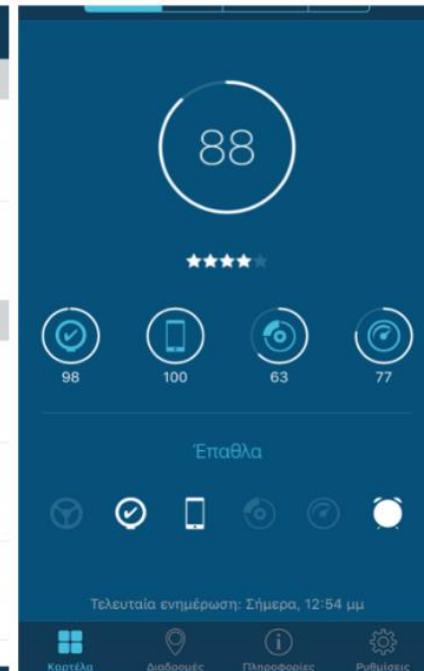
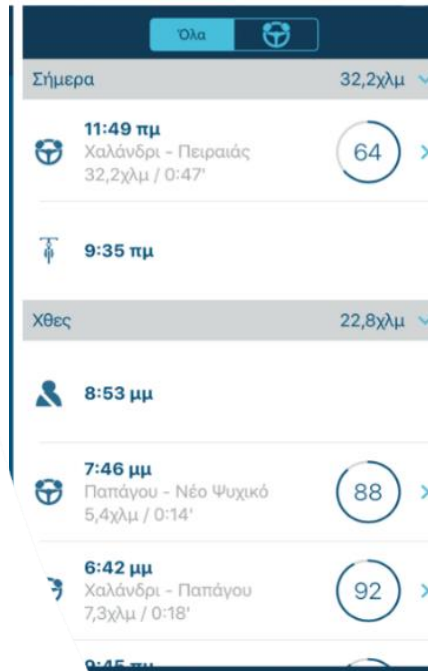
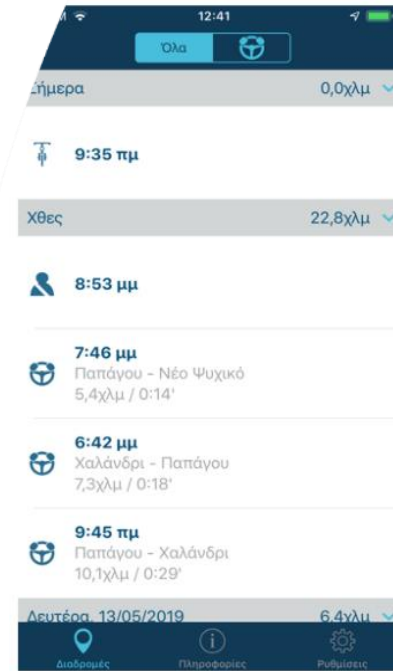
The BeSmart Application

➤ Driving behavior characteristics

- Speeding
- Harsh braking/ acceleration/ cornering
- Mobile phone use (car drivers' application)

➤ Travel behavior characteristics

- Total distance
- Road network type
- Risky hours driving
- Vehicle type



Smartphone data collection (1/2)

- A mobile application to **record user's driving behavior** (automatic start / stop)
- A variety of APIs is used to read mobile phone **sensor data**
- Data is transmitted from the mobile App to the **central database**
- Data are **stored** in a sophisticated database where they are **managed and processed**



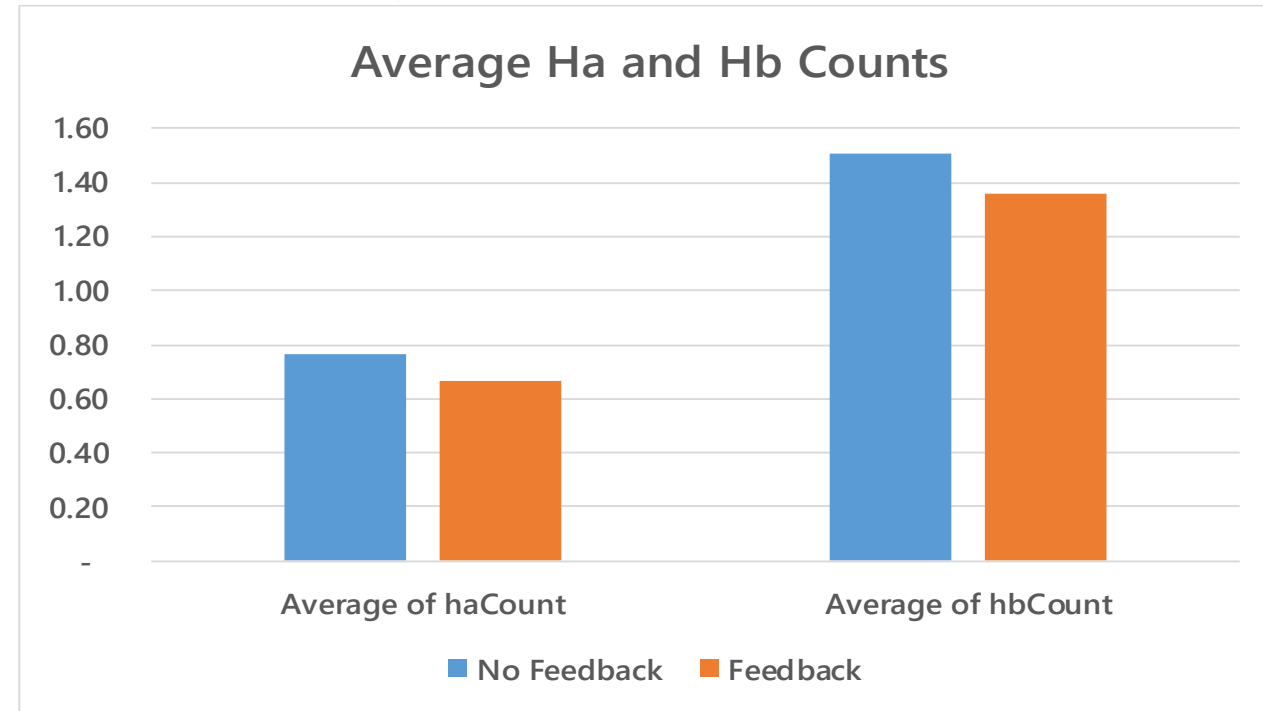
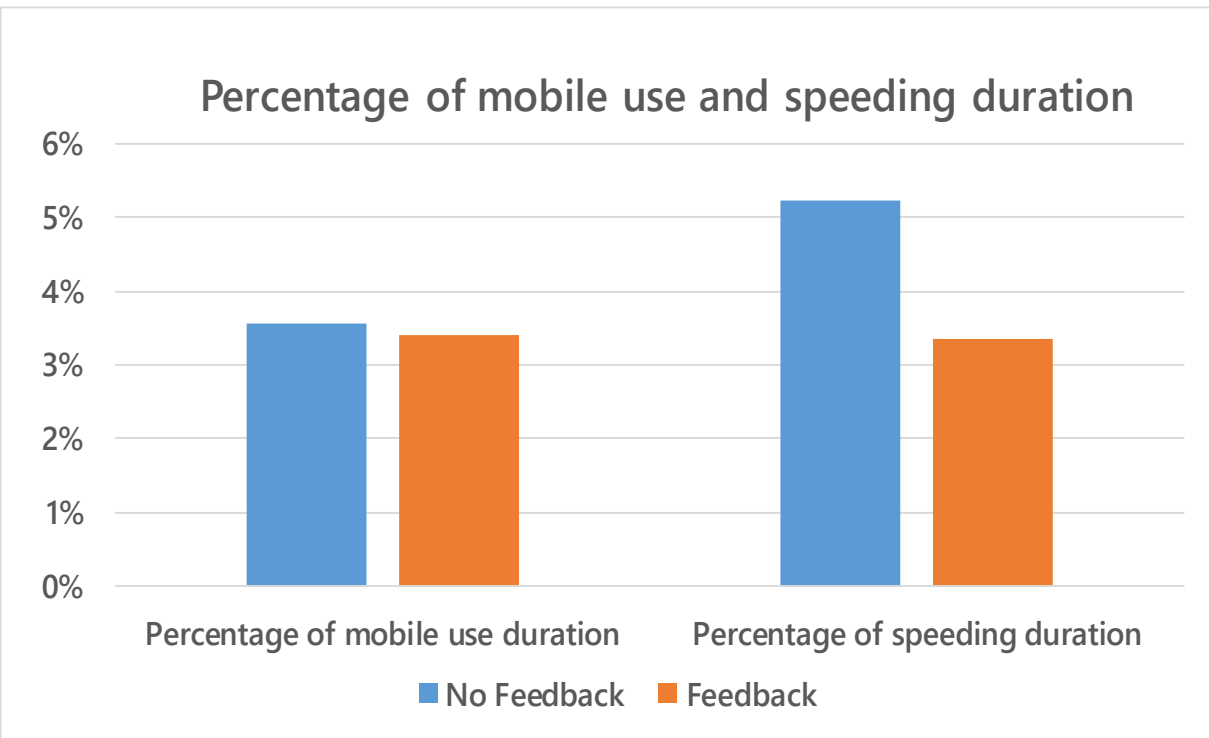
Smartphone data collection (2/2)

- Indicators are designed using:
 - machine learning algorithms
 - big data mining techniques
- The database analyzed was in .csv format
 - Drivers' trips are stored per row, the characteristics of which are stored in each column's variables
- State-of-the-art technologies and procedures in compliance with standing Greek and European personal data protection laws (GDPR)



Descriptive statistics – car drivers

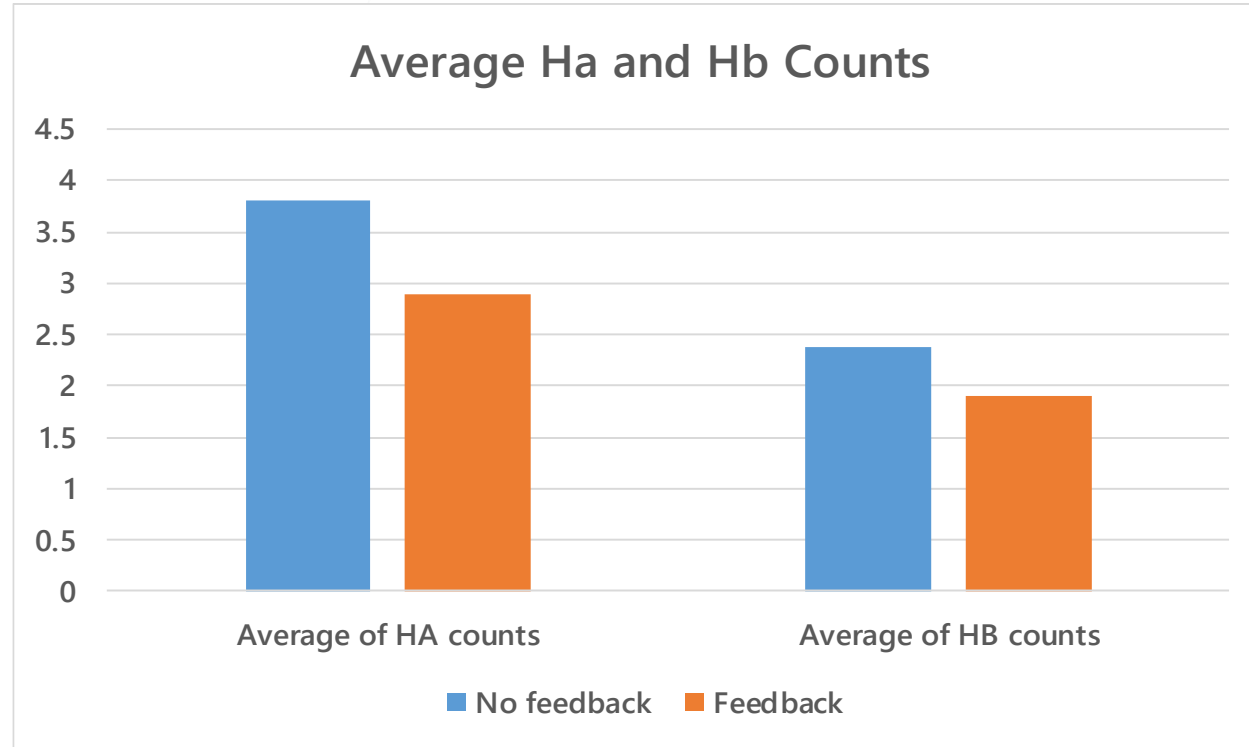
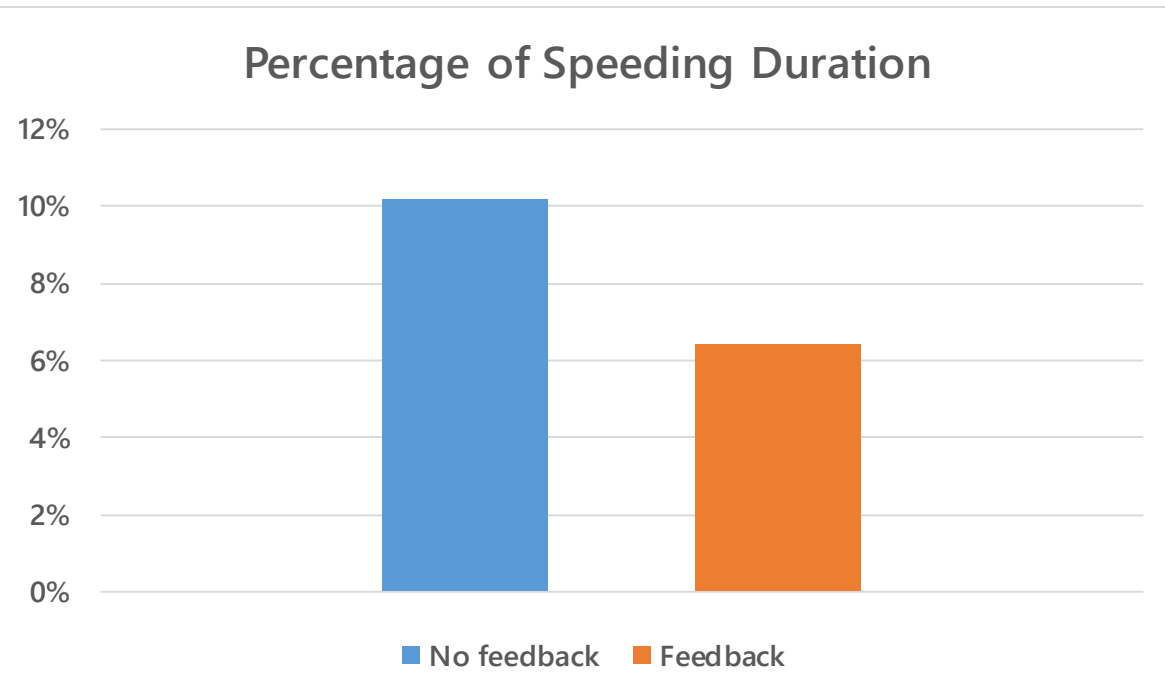
- Both types of harsh events (accelerations and brakings) are **reduced in the 2nd phase** of the experiment



- The percentage of driving above the speed limits and driving while distracted by the mobile phone is **reduced in the 2nd phase** of the experiment

Descriptive statistics – PTW riders

- Both types of harsh events (accelerations and brakings) are **reduced in the 2nd phase** of the experiment

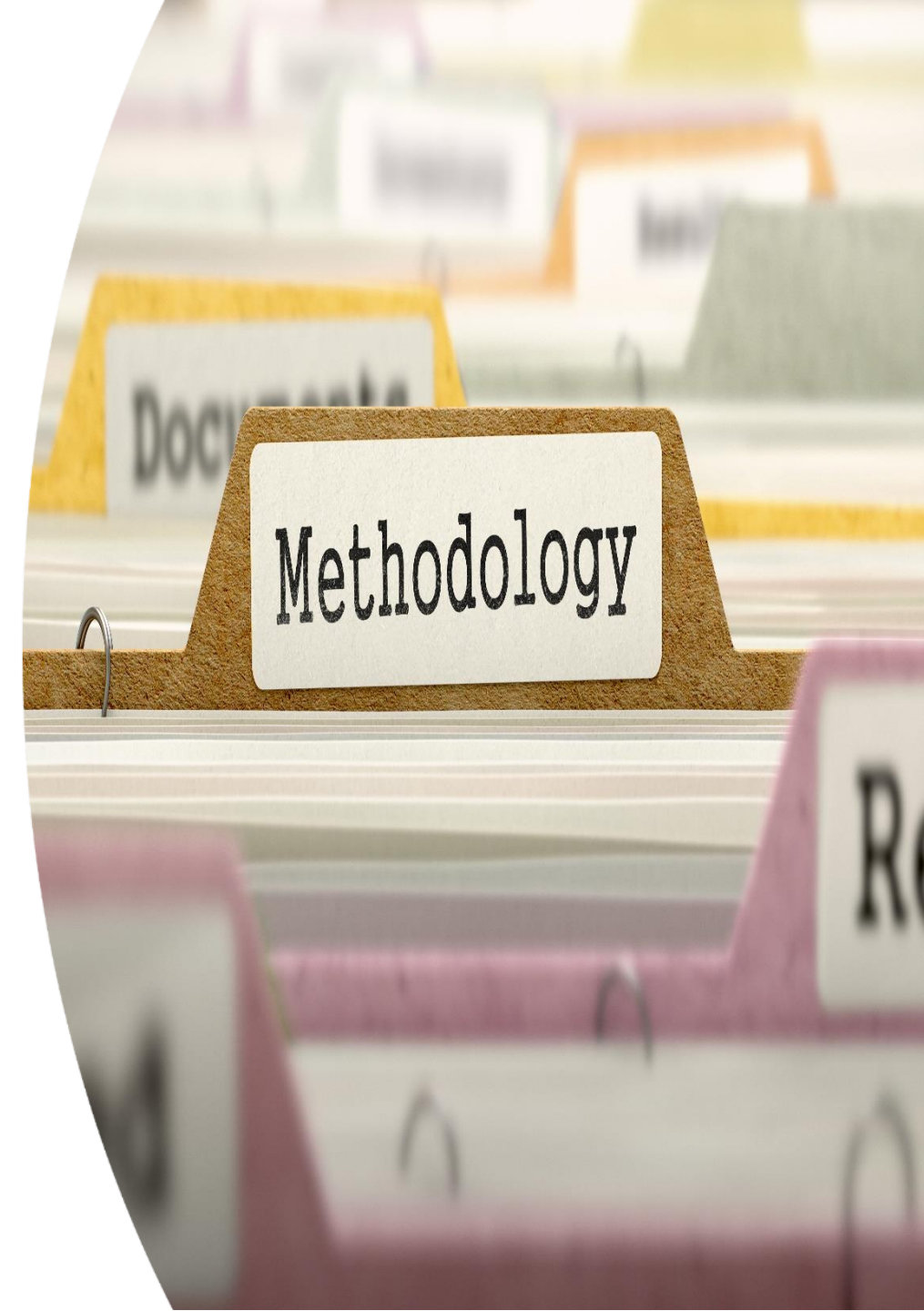


- The percentage of driving above the speed limits is **reduced in the 2nd phase** of the experiment

Theoretical Background

- Selection of statistical method:
 - Need for fraction prediction – **percentage of speeding time**
 - Generalized Linear Models (GLM) - **Poisson Regression**
 - Introduce random effects to capture different driving behaviors and extend GLMs as **Generalized Linear Mixed-Effects Models** (GLMMs), given by the following formula:

$$\log(\lambda_i) = \beta_{0i} + \beta_{ji}x_{ji} + \beta_{n-1}x_{n-1} + \varepsilon$$



Results (1/2) – car drivers

GLMMs for the percentage of driving time above the speed limit

| Trip Parameter | Estimate | s.e. | p-value | Sig. | Rel. Risk Ratio |
|---|----------|--------|---------|------|-----------------|
| Intercept | 1.702 | 0.0614 | <0.001 | *** | 5.485 |
| Exp. phase (0=no feedback, 1=feedback) | -0.392 | 0.006 | <0.001 | *** | 0.675 |
| Total trip duration (s) | 0.204 | 0.036 | <0.001 | *** | 1.226 |
| Number of harsh accel. per trip (count) | 0.161 | 0.002 | <0.001 | *** | 1.175 |
| Trip distance during risky hours [22:00-05:00] | 0.029 | 0.001 | <0.001 | *** | 1.029 |
| Morning peak hour [06:00-10:00] (0=yes, 1=no) | 0.027 | 0.008 | <0.001 | *** | 1.027 |
| Afternoon peak hour [16:00-20:00] (0=yes, 1=no) | -0.236 | 0.007 | <0.001 | *** | 0.790 |

Results (2/2) – PTW riders

GLMMs for the percentage of driving time above the speed limit

| Trip Parameter | Estimate | s.e. | p-value | Sig. | Rel. Risk Ratio |
|---|----------|-------|---------|------|-----------------|
| Intercept | 1.898 | 0.276 | <0.001 | *** | 6.672 |
| Exp. phase (0=no feedback, 1=feedback) | -0.145 | 0.013 | <0.001 | *** | 0.865 |
| Total trip duration (s) | 0.194 | 0.095 | 0.042 | * | 1.214 |
| Number of harsh accel. per trip (count) | 0.248 | 0.005 | <0.001 | *** | 1.281 |
| Trip distance during risky hours [22:00-05:00] | 0.018 | 0.003 | <0.001 | *** | 1.018 |
| Morning peak hour [06:00-10:00] (0=yes, 1=no) | 0.067 | 0.015 | <0.001 | *** | 1.069 |
| Afternoon peak hour [16:00-20:00] (0=yes, 1=no) | -0.286 | 0.015 | <0.001 | *** | 0.751 |

Conclusions (1/2)

- Both **car drivers and PTW riders indicate similar behavior** while exceeding the speed limits
- **Trip length** and driving during the **morning rush and night-time risky hours** are exposure metrics positively correlated with the odds of speeding
- **Harsh accelerations** are also associated with the odds of someone exceeding the speed limits, outlining a pattern of an overall unsafe driving behavior



Conclusions (2/2)

- The present results capture and quantify the **positive effects of driver feedback** on one of the most important human risk factors; speeding
- The ultimate objective when providing feedback to drivers is to:
 - Trigger their **learning and self-assessment process**, thus enabling them to gradually improve their performance
 - Monitor the **shift of driving behaviour** as the application provides feedback



Future research

- Investigating the impact of **different types of personalized feedback** communicated through the project application:
 - Incentives within a social gamification scheme, with personalized target setting,
 - Benchmarking and comparison with peers
- Examinations of the **impact of feedback over time**, the influence of its evolution on drivers and its consistency
- Microscopic data analysis of the collected database through **machine learning techniques**





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