

# Road Safety Forecasts in Five European Countries Using Structural Time-Series Models

Constantinos Antoniou, Eleonora Papadimitriou & George Yannis - National Technical University of Athens, Greece



## Abstract

Modeling road safety development is a complex task, which needs to consider both the quantifiable impact of specific parameters, as well as the underlying trends that cannot always be measured or observed. The objective of this research is to apply structural time series models for obtaining reliable medium- to long-term forecasts of road traffic fatality risk using data from five countries with different characteristics from all over Europe (Cyprus, Greece, Hungary, Norway and Switzerland). Two structural time series models are considered: (i) the local linear trend model and the (ii) latent risk time-series model. Furthermore, a structured decision tree for the selection of the applicable model for each situation (developed within the DACOTA research project) is outlined. First, the fatality and exposure data that are used for the development of the models are presented and explored. Then, the modeling process is presented including the model selection process, the introduction of intervention variables and the development of mobility scenarios. The forecasts using the developed models appear to be realistic and within acceptable confidence intervals. The proposed methodology is proved to be very efficient for handling different cases of data availability and quality, providing an appropriate alternative from the family of structural time series models in each country. A concluding section providing perspectives and directions for future research is finally presented.

## **Background & Objectives**

- A number of approaches for modelling road safety developments have been proposed During the last decade, the modeling approach of structural time-series models, such as those proposed by Harvey & Shephard (1993) is applied by several researchers
- In this approach, which belongs to the family of unobserved component models, latent variables are decomposed into components which are incorporated into the structural models

### **Objectives**

- to apply structural time series models for obtaining reliable medium- to long-term forecasts of fatality risk
- to develop models for modeling the relationship between mobility and risk and examine the effect of mobility on risk
- to develop a structured methodology for the selection of the optimal forecasting models. based on a number of criteria, diagnostics and measures of goodness of fit to demonstrate that the developed approach is robust and applicable to different
- conditions and environments, by applying it to data from five European countries with very different characteristics

## Methodology

- Structural time-series models: Local Linear Trend (LLT) and Latent Risk Time-Series (LRT) models
- A basic concept in road safety is that the number of fatalities is a function of the road risk and the level of exposure of road users to this risk. In order to model the evolution of fatalities it is required to model the evolution of two parameters; a road safety indicator and an exposure indicator

Traffic volume = Exposure Number of fatalilties = Exposure × Risi

When the logarithm of the Equations is taken (and the error term is explicitly written out) the "measurement equations" of the model can be rewritten as

> Log Traffic volume = log exposure + random error in traffic volume Log Number of fatalities = log exposure + log risk + random error of fatalities

 The latent variables [log (exposure) and log (risk)] need to be further specified by "state" equations, which, once inserted in the general model, describe the development of the latent variable

#### LLT model

 $\log Number of Fatalities_{,} = \log LatentFat_{,} + \varepsilon_{,}$ Measurement equation State equations Level(log LatentFat<sub>1</sub>) = Level(log LatentFat<sub>1</sub>) + Slope(log LatentFat<sub>1</sub>) +  $\xi_t$  $Slope(log(LatentFat_{t}) = Slope(log LatentFat_{t-1}) + \zeta_{t}$ 

#### LRT model

Measurement equations	$\log Traffic Volume_i = \log Exposure_i + \varepsilon_i^{c}$		
	$\log Number of Fatalities_i = \log Exposure_i + \log Risk_i + \varepsilon_i^{f}$		
State equations	$\begin{split} Trend(\log Risk_{i}) &= Level(\log Risk_{i-1}) + Slope(\log Risk_{i-1}) + \xi_{i}^{'}\\ Slope(\log Risk_{i}) &= Slope(\log Risk_{i-1}) + \xi_{i}^{'} \end{split}$		
	$Level(\log Exposure_{t}) = Level(\log Exposure_{t-1}) + Slope(\log Exposure_{t-1}) + \xi_t^{e}$		
	$Slope(\log Exposure_i) = Slope(\log Exposure_{i-1}) + \xi_i^{e}$		

The Equation now includes the Risk (and not the fatalities)

### SUTSE (Seemingly Unrelated Time Series) mode

A third class of models, used as a preliminary step in establishing whether the two timeseries may be correlated



## Model selection logic

- The family of structural time-series models lends to a large number of assumptions that distinguish the resulting models into different categories.
- Within the framework of the DaCaTA research project, a decision process and model selection logic has been developed in which the following steps are considered
- Investigate exposure: the first step in every modeling effort is to assess the quality and characteristics of the underlying
- Do the available exposure data make sense?
- Can any sudden changes in the level or slope be explained from some real events?
- 2. Establish whether the two series are statistically related: a SUTSE model is developed and based on the diagnostics the modeler needs to decide whether the two time-series are correlated

If on the other hand, none of the hypotheses can be rejected, then there is no evidence that the two time-series are

3. Determine whether an LLT or an LRT model should be pursued: □ If one or more of the null-hypotheses regarding the correlation of the disturbances is rejected, the time-series may be

correlated and therefore an LLT model would be more appropriate.

Greece

Cypru

## Model application Data collection & analysis

related and therefore an LRT can be estimated

## Switzerland







#### Models by country Model selection process for Switzerland

Model type	LRT	LRT	LRT
	full	restricted	restricted
			with
			interventions
Model Criteria			
ME10 Fatalities	-6037	-5374	-4918
MSE10 Fatalities	5.56827	4.79550	4.35124
log likelihood	18156	1/6/5	1/0/1
AR.	-30202	-333222	-34113
variance of scare components	1.015.04		
Level exposure	1.01E-04	7.000.04.0	7 705 04 8
Slone exposure	6.46E-06	4 15E-05 *	6.84F-06 *
Slore risk	9.41E-06		
Correlations between state components			
level.level	0.64		
slope-slope	1		
Observation variance			
Observation variance exposure	2.95E-06	5.95E-05 *	7.32E-05 *
Observation variance risk	4.18E-06	2.99E-04	2.47E-04
Interventions			
(1993 exposure level)			-0.0501062 *
Model Quality			
Box-Ljung test 1 Exposure	0.228	121.897	136.467
Box-Ljung test 2 Exposure	0.801	241.477	503.337
Box-Ljung test 3 Exposure	0.8525	329.751	583.505
Box-Ljung test 1 Fatalities	216.579	286.154	263.737
Box-Ljung test 2 Fatalities	255.335	316.426	265.737
Box-Ljung test 3 Fatalities	311.375	376.553	33.562
Heteroscedasticity Test Exposure	0.386	0.454	0.807
received as a set of the set of t	269.171	302.679	280.834
Normality Test standard Paciduals Exposure	3.39954*	0.212	329.758
Normality Test output Ave Rec Exposure	0.0189	0.312	152 242
Normality Test output Aux Res Exposite	124 914	159 349	183.043
Normality Test State Aux Res Level exposure	338.426	307.695	0.0385
Normality Test State Aux Res Slone exposure	129.975	0.706	0.183
	3.574	8.381*	7.704*
Normality Test State Aux Res Level risk			

The full LRT model suggests that both the level and slope of both components are non significant (& common components Best fitting restricted LRT: fixed level exposure & slope risk Intervention variables: a change in exposure level on 1993



## Mobility scenarios

Fatality forecasts on the basis of three different scenarios for exposure: the exposure as predicted from the selected LRT model plus/minus one standard deviation



## Overview for the five countries

	Cyprus	Greece	Hungary	Norway	Switzerland
Data available	1990-2010	1960-2010	1970-2010	1970-2009	1975-2010
Exposure	Fuel consumption	Vehicle fleet	Passenger kilometres	Vehicle kilometres	Vehicle kilometres
Recession effect	Yes	No	Yes	No	No
Information on inverventions	No	Yes	Yes	No	No
Data used	1990-2010	1960-2010	1993-2010	1970-2009	1975-2010
Model type	LRT	LLT	LT	LRT	LRT
Interventions	No	Yes	Yes	No	Yes
Forecast 2020	Yes	Yes	Yes	Yes	Yes
Mobility scenario	Yes	No	No	Yes	Yes

### Conclusions

- The proposed methodology contributes meaningful steps for model selection, starting with SUTSE modeling and proceeding to LLT / LRT, full or restricted, on the basis of sound criteria in each case
- Nevertheless, a good knowledge of the road safety and socioeconomic situation in the examined countries was still necessary, not only for understanding the description and forecasts of the developments, but also for making decisions in data handling, introduction of intervention variables etc.
- The proposed methodology was proved to be very efficient for handling different cases of data availability and quality, providing an appropriate alternative from the family of structural time series models in each case.
- The estimated forecasts in all 5 countries appear to be realistic and within acceptable confidence intervals
- These results may be useful for understanding past developments, the dynamics and particularities of the relationship between exposure and fatality risk, and the effects of safety interventions or other socio-economic events on mobility and road safety.
- The estimated forecasts reflect the future situation if the existing policy efforts and the socio-economic context extent to the future, and this may be motivating for devoting additional efforts in outperforming these forecasts.

## **Key references**

- Commandeur J.F.C., Bijeveld, F., Bergel R., Antoniou C., Yannis G., Papadimitriou E. (2012). On statistical inference in time series analysis of the evolution of road safety. Article In Press, Accident Analysis & Prevention, Special Issue on SafetyNet. Duppet E & Martensen H (Eds.) (2012) Enrecasting road traffic statities in European countries. Deliverable 4.4 of the EC EP7 project DaCoTA
- And the second sec
- Lassarre, S. (2001). Analysis of progress in road safety in ten European countries. Accident Analysis and Prevention 33, pp. 743 751
- Yannis G., Antoniou, C., Papadimitriou E., Katsochis D. (2011). When may road fatalities start to decrease? Journal of Safety Research 42, pp. 17-25.



restricted with

interventions interve

65.82

1.00E-09 1.88E-03 \*

0.220

2.67E-03\*

-0.080 \* -0.211 \* 0.147 \*

0.29 2.78 4.03 150.267 188.584 322.822

0.76 263.094

2.06 182.026

1.17 118.117

1.1 0.943

tes significant at 99.9% le

58253.62 167835 224559

967.3 156.941 -313.612

3.84E-03 \* 3.16E-04 \*

1.45E-06 5.40E-04

1.1 1.63 1.33 0.84

0.76

1.71 0.16

1.76

118.25 52.96

9.22E-05 6.53E-04 1.08E-04 8.10E-06

1.91 2.27 0.47 2.45 1.98

5.89 0.92



Final models for the other countries

Model Criteria

Variance of state

Correlations be

y Test State Aux Res Lev

Test State Aux Res Slop

lote: \* denotes significant at 95% leve

/ Test State Aux Res Level risk / Test State Aux Res Slope risk

evel expe