

ROAD, TRAFFIC AND HUMAN FACTORS OF PEDESTRIAN CROSSING BEHAVIOUR: INTEGRATED CHOICE AND LATENT VARIABLES MODELS

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ABSTRACT

1 This paper aims to jointly analyze road, traffic and human factors of pedestrian crossing
2 behavior, through the development of Integrated Choice and Latent Variables (ICLV) models.
3 The analysis uses recent research as a starting point, in which a two-stage approach was
4 successfully tested, including a separate estimation of human factors and choice models. Data
5 from a dedicated field survey are used, in which pedestrian field observations of road crossing
6 behavior in different road and traffic scenarios were combined with a questionnaire on
7 pedestrian attitudes, perceptions, motivations and declared behaviors. ICLV models were
8 developed for four different road types, namely major urban arterials, main roads, secondary
9 roads and residential roads. The results suggest that the effect of traffic conditions on pedestrian
10 crossing choices was more important on main and secondary urban roads, while on major urban
11 arterials and on residential roads it was non-significant. As regards the effects of human factors,
12 a ‘risk’ latent variable was found to enhance the explanatory power of most of the models. This
13 variable was estimated on the basis of different indicators in each case, reflecting a clear ‘risk-
14 taking’ tendency on major and main roads and an ‘optimization tendency’ on minor roads.
15 Overall, it is indicated that the integration of human factors in pedestrian crossing models
16 provides meaningful and insightful results, and may be advantageous compared to the two-
17 stage approach.

18

19 **Key-words:** pedestrian behavior; human factors; integrated choice and latent variables models.

20 **BACKGROUND AND OBJECTIVES**

21

22 Modelling pedestrian crossing behavior in urban areas has attracted the interest of many
23 researchers during the last few decades, as it may assist in the better understanding of the
24 interaction between pedestrians and the road and traffic environment, and of the way they
25 balance the need for speed and comfort with the costs of risks and delays (1, 2, 3). Studying
26 pedestrians' crossing behavior can eventually lead to the better design and management of
27 urban road networks in order to improve pedestrians' mobility and safety (3).

28 Signalized junctions provide a protected crossing phase for pedestrians. Nevertheless,
29 it is often observed that pedestrians prefer to use the available traffic gaps for crossing, make
30 mid-block and diagonal crossings, etc. (4). Pedestrians generally experience shorter delays than
31 other road users because of their flexibility and adaptability, but the accident risk they are
32 exposed to is higher (5,6).

33 Road and traffic factors affecting pedestrian crossing decisions have been analyzed by
34 means of gap acceptance models (7, 8), level of service approaches (9, 10), or discrete choice
35 models (4, 11, 12). Another part of the related literature is focused on psychological, attitudinal,
36 perceptual and motivational factors (13, 14, 15). However, these human factors are rarely
37 incorporated in pedestrian behavior models (16).

38 A first step for the combined analysis of road, traffic and human factors of pedestrian
39 behavior was presented in (16), where a two-step approach was implemented: first, human
40 factors were calculated by means of Principal Component Analysis on the responses of a
41 questionnaire and then, these factors were introduced as additional explanatory variables in
42 crossing choice models based on field observations. This approach already provided some
43 interesting results, but has some known limitations, namely the fact that the error in the
44 estimation of human factors is not taken into account (as these are separately estimated) and
45 this may induce measurement errors in their effects as explanatory variables.

46 A more pertinent technique for analyzing human factors in discrete choice models are
47 Integrated Choice and Latent Variables models (ICLV). ICLV models enhance the
48 understanding of the choice process by merging classic choice models with the structural
49 equation approach for latent variables, and are a very promising method for capturing attitudes
50 and perceptions of decision makers (17, 18). These models have been tested in the fields of
51 transport economics, activity planning and transport mode choice (19, 20, 21). However, they
52 have not been used so far for the analysis of pedestrians' choices. This paper therefore presents
53 a more sophisticated and appropriate methodology for the analysis of the data in (16).

54 More specifically, the objective of this paper is to develop choice models of pedestrian
55 crossing behavior, integrating the effect of human factors (i.e. pedestrian attitudes, perceptions,
56 motivations and behavior) together with road and traffic factors. More specifically, the paper
57 aims to further analyze data from the above mentioned dedicated survey, combining field
58 observations of pedestrian trajectories and a questionnaire on pedestrian human factors (16), in
59 order to develop ICLV models of pedestrian crossing behavior.

60 Key research parameters are road type, traffic control, traffic volume, pedestrian
61 demographics, as well as pedestrian risk-taking attitudes and perceptions, walking motivations,
62 opinion on drivers etc. For detailed research hypotheses please see (16).

63

64

65 **DATA COLLECTION**

66

67 In this research, a particular data collection scheme was implemented [see also (16)]. Crossing
 68 behavior at urban pedestrian trips was recorded along with the conditions of the traffic and road
 69 environment. Attitudes, perceptions and behavior with regards to road crossing and accident
 70 risk were captured using a questionnaire.

71

72 **Field survey design**

73

74 The field survey designed and implemented in the present research comprises three walking
 75 conditions and eight crossing scenarios. Survey participants were asked to take a trip in the
 76 Athens city center, Greece, from Kolonaki square to Evangelismos metro station and back,
 77 according to predefined routes presented on the map (see Figure 1). The eight survey scenarios
 78 were developed so that the choice sets for crossings can be clearly defined; only one crossing
 79 of interest will occur for each one of the scenarios, referred to as ‘primary’ crossing (3, 12).

80 All types of traffic conditions (free flow to congestion) are encountered during the day
 81 for the major urban arterial and the main urban road, while for the minor/ residential roads low
 82 to moderate traffic is mainly encountered throughout the day. No major variation of traffic is
 83 observed during the day in that area. The survey took place on weekdays’ morning and
 84 afternoon hours, with daylight, good weather, fairly constant traffic conditions and no
 85 congestion recorded.

86 The number of road links for each scenario and the geometric and traffic control
 87 characteristics of the roads are summarized in Table 1.

88

89 **TABLE 1 Road type and geometric / traffic control characteristics of the survey**
 90 **scenarios**

91

Route	Scenario	Street name	Road type	Directions	Lanes	Separation	Traffic signals	Roadside parking	Number of links
From Kolonaki to Evangelismos	1	Patr.Ioakeim	Main	2	2	No	Yes	No	4
	2	Ploutarchou	Secondary	2	2	No	No	Yes	4
	3	Vas.Sofias	Major	2	6	Yes	Yes	No	2
From Evangelismos to Kolonaki	4	Vas.Sofias	Major	2	6	Yes	Yes	No	2
	5	Ploutarchou	Secondary	2	2	No	No	Yes	2
	6	Karneadou	Minor	1	1	No	No	Yes	2
	7	Irodotou	Minor	1	1	No	No	Yes	2
	8	Patr.Ioakeim	Main	2	2	No	Yes	No	2

92

93

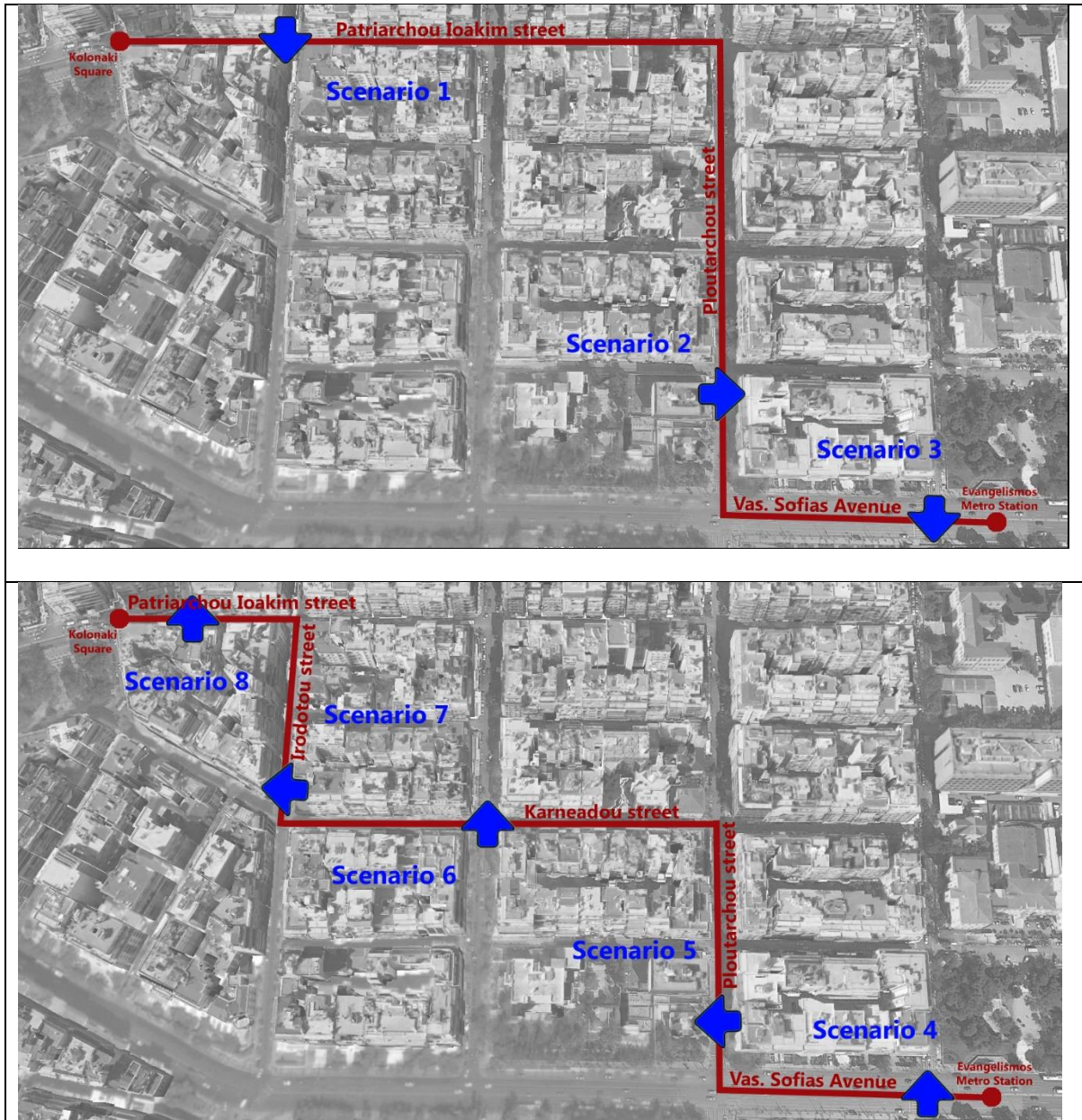


FIGURE 1 Presentation of the crossing scenarios on the survey site map

Questionnaire design

A questionnaire was developed on the basis of several questionnaires from the existing literature (13, 15, 22, 23), and was structured as a list of items to be rated on the basis of 5-point Likert scales (always/never or agree/disagree scales). The questionnaire includes 5 sections, as shown in Table 2:

TABLE 2 Survey questionnaire

B	How many times per week do you travel by each one of the following modes*:
B1_i	Public transport (metro, bus, trolley bus, tramway)
B1_ii	Pedestrian
B1_iii	Passenger car (driver or passenger)

	Last week, how many kilometers did you travel by each one of the following modes**:
B2_i	Passenger car (driver or passenger)
B2_ii	Pedestrian
B2_iii	Public transport (metro, bus, trolley bus, tramway)
	As a pedestrian, how much would you agree with each one of the following statements***:
B3_i.	I walk for the pleasure of it
B3_ii	I walk because it is healthy
B3_iii	In short trips, I prefer to walk
B3_iv	I prefer taking public transportation (buses, metro, tramway, etc.) than my car
B3_iv	I walk because I have no other choice
C	As a pedestrian, how much would you agree with each one of the following statements***:
C1_i.	Crossing roads is difficult
C1_ii.	Crossing roads outside designated locations increases the risk of accident
C1_iii.	Crossing roads outside designated locations is wrong
C1_iv	Crossing roads outside designated locations saves time
C1_v	Crossing roads outside designated locations is acceptable because other people do it
C2_i	I prefer routes with signalized crosswalks
C2_ii	I try to make as few road crossings as possible
C2_iii	I try to take the most direct route to my destination
C2_iv	I prefer to cross diagonally
C2_v	I try to take the route with least traffic to my destination
C2_vi	I am willing to make a detour to find a protected crossing
C2_vii	I am willing to take any opportunity to cross
C2_viii	I am willing to make dangerous actions as a pedestrian to save time
D	Compared to other pedestrians, how much do you agree that***:
D_i	I am less likely to be involved in a road crash than other pedestrians
D_ii	I am faster than other pedestrians
D_iii	I am more careful than other pedestrians
E	As a pedestrian, how often do you adopt each one of the following behaviors****:
E1_i.	I cross diagonally
E1_ii	I cross at midblock at major urban arterials
E1_iii	I cross at midblock at urban roads
E1_iv	I cross at midblock in residential areas
E1_v	I cross at midblock when I am in a hurry
E1_vi	I cross at midblock when there is no oncoming traffic
E1_vii	I cross at midblock when I see other people do it
E1_viii	I cross at midblock when my company prompts me to do it
E1_ix	I prompt my company to cross at midblock
E1_x	I cross at midblock when there is a shop I like on the other side
E1_xi	I cross even though the pedestrian light is red
E1_xii	I walk on the pavement rather than on the sidewalk
E2_i	I cross between vehicles stopped on the roadway in traffic jams
E2_ii	I cross without paying attention to traffic
E2_iii	I am absent-minded while walking
E2_iv	I cross while talking on my cell phone or listening to music on my headphones
E2_v	I cross even though obstacles (parked vehicles, buildings, trees, etc.) obstruct visibility
E2_vi	I cross even though there are oncoming vehicles
F	As a pedestrian, how much would you agree with each one of the following statements***:
F1_i	Drivers are not respectful to pedestrians
F1_ii	Drivers drive too fast
F1_iii	Drivers are aggressive and careless
F1_iv	Drivers should always give way to pedestrians
F1_v	When there is an accident, it is the driver's fault most of the times
F1_vi	I let a car go by, even if I have right-of-way
	* (1:never, 2: less than once a week, 3:once a week, 4: more than once a week, 5:every day)
	** (1:1-2 km, 2: 3-5 km, 3:5-20 km, 4: 20-50 km, 5: >50 km)
	*** (1:strongly disagree, 2: disagree, 3:neither agree nor disagree, 4: agree, 5:strongly agree)
	**** (1:never, 2: rarely, 3:sometimes, 4: often, 5:always)

107 Survey procedure

108

109 The data collection took place in the period July - December 2013 with 75 participants in total.
 110 Participants were students of the National Technical University of Athens (NTUA) and young
 111 professionals. Fifty three percent of the survey participants were males, 50% of the participants
 112 were 18-24 years old, 27% were 25-34, 20% were 35-45 and 3% were >45 years old.

113 Half of the participants carried out the field experiment after filling in the questionnaire,
 114 and half of the participants first carried out the field experiment and then filled in the
 115 questionnaire; in this way, the survey was counterbalanced in order to minimize the bias of
 116 participants possibly adapting their declared behavior to their observed behavior and vice-
 117 versa. The observed crossing behavior of participants does not appear to be affected by the
 118 order of the tasks. Table 3 shows a comparison of observed mid-block crossing for the eight
 119 scenarios and in total, between the participants who filled the questionnaire before the walking
 120 task, and those who filled it after - no significant differences are noticed.

121

122 **TABLE 3 Comparison of observed crossing behavior for filling in the questionnaire**
 123 **before or after the walking task**

124

		Observed share of crossings		
		Mid-block	Junction	Total
All participants		30,0%	70,0%	100,0%
Before		28,7%	71,3%	100,0%
After		31,5%	68,5%	100,0%
Main roads	Before	23,1%	76,9%	100,0%
	After	27,3%	72,7%	100,0%
Secondary roads	Before	46,8%	53,2%	100,0%
	After	52,4%	47,6%	100,0%
Major roads	Before	5,1%	94,9%	100,0%
	After	3,0%	97,0%	100,0%
Minor roads	Before	40,0%	60,0%	100,0%
	After	40,0%	60,0%	100,0%

125

126 The participants were informed about the purpose of the experiment and the fact that
 127 they would be followed along this trip by a researcher who would be unobtrusively recording
 128 their behavior. This allows for control over the experiment design (e.g. specific route and
 129 scenarios to be examined) and for a larger amount of questionnaire data to be collected, and
 130 also complies with privacy protection and informed consent needs. However, there are
 131 limitations, as it is possible that participants may alter their behavior if they know that they are
 132 being observed. The fact that participants did declare and actually performed risk-taking and
 133 non-compliant crossing behaviors within the survey indicates that the degree to which they
 134 may have altered their behavior is small.

135 Once the participant started the trip, a trained researcher followed him or her at a
 136 distance of approximately 35 meters, in order to have a sufficient view of the participant and
 137 remain unobtrusive, and recorded data on each road link by filling-in a predefined form. For
 138 the walking speed data, the researcher recorded the distance walked and the time taken to walk
 139 for each road link (from one junction to the other) of the trip. For the traffic volume data, the
 140 researcher assessed the traffic conditions on each road link as “empty”, low traffic, high traffic
 141 or congestion; for the distinction between low and high traffic in particular, an approximate
 142 criterion of vehicle headways higher or lower than 3 seconds was used.

143

144 **ANALYSIS METHODOLOGY**

145

146 A probabilistic discrete choice is involved in determining the location of each primary crossing
 147 from the alternatives of the examined scenario (choice set). Previous research (12, 16) has
 148 shown that a sequential choice behavior appears to be the optimal assumption for pedestrian
 149 crossing choices. This sequential choice process involves a decision on each road link of the
 150 choice set: crossing at mid-block (MB), crossing at junction (J) or no crossing (No) (see Figure
 151 2). If no crossing takes place on a given road link, the same choice set is examined on the next
 152 road link, and so on, until a primary crossing is made, and therefore the rest of the choice set
 153 (i.e. the subsequent road links for this scenario) are not considered.

154

155 **Integrated Choice and Latent Variables Models (ICLV)**

156

157 In an ICLV model, the discrete choice model includes latent variables that capture attitudes
 158 and perceptions of the pedestrians. The latent variable model is composed of a group of
 159 “structural equations” describing the latent variables as a function of observable exogenous
 160 variables, and a group of “measurement equations”, linking the latent variables to the
 161 observable indicators. The key feature of the proposed modelling framework is that the latent
 162 variables can be calculated from the observable variables once the model parameters are
 163 estimated (integration).

164

165 The equations of the ICLV model follow, in the simple case of a binary choice model
 166 (choice alternatives i and j) with two latent variables (Z_1 and Z_2), each one measured by two
 167 observed variables (I_1, I_2, I_3, I_4) (19):

167

168 Structural equations of the ICLV model

169
$$U_{in} = b'X_{in} + b_1\tilde{Z}_{1n} + b_2\tilde{Z}_{2n} + \varepsilon_{in}$$

170
$$U_{jn} = b'X_{jn} + \varepsilon_{jn}$$

171

172 Measurement equation of the ICLV model

173
$$y_n = \begin{cases} 1, & \text{if } U_{in} > U_{jn} \\ 0, & \text{otherwise} \end{cases}$$

174

175 Structural equations of the latent variables model

176
$$Z_{1n} = \alpha_1 W_{in} + \omega_{1n}$$

177
$$Z_{2n} = \alpha_2 W_{in} + \omega_{2n}$$

178

179 Measurement equations of the latent variables model

180
$$I_{1n} = \lambda_1 Z_{1n} + v_{1n}$$

181
$$I_{2n} = \lambda_2 Z_{1n} + v_{2n}$$

182
$$I_{3n} = \lambda_3 Z_{2n} + v_{3n}$$

183
$$I_{4n} = \lambda_4 Z_{2n} + v_{4n}$$

184

185 where: U_{in}, U_{jn} denote the utility of each alternative respectively, for individual n ; X_{in}, X_{jn}
 186 are sets of observed variables; Z_{1n}, Z_{2n} are the latent variables (actually the “components”
 187 accounting for most of the variability of the respective latent variables); $I_{1n}, I_{2n}, I_{3n}, I_{4n}$ are
 188 sets of the indicators of the latent variables Z_{1n}, Z_{2n} respectively; $\tilde{Z}_{1n}, \tilde{Z}_{2n}$ are the fitted
 189 values of the latent variables, once they are estimated by the structural equations of the latent
 190 variable model; W_{1n}, W_{2n} are sets of observed variables (characteristics of respondent n);
 191 $\varepsilon_{in}, \varepsilon_{jn}$ are extreme value distributed errors; $\omega_{1n}, \omega_{2n}, v_{1n}, v_{2n}, v_{3n}, v_{4n}$ are sets of

192 (multivariate normally distributed) errors; b' , b_1 , b_2 , α_1 , α_2 , λ_1 , λ_2 , λ_3 , λ_4 are sets of unknown
193 parameters to be estimated.

194 The measurement equations indicators I_{in} in the present research are discrete ordered,
195 as the pedestrians were asked to respond on a 5-point Likert scale, ranging from “never” to
196 “always”, or from “strongly disagree” to “strongly agree”. The ‘cumulative logit’ link is used
197 in ordered models. The notation γ_{ij} refers to cumulative probabilities, while π_{ij} designates
198 “ordinary” probabilities. Formally, cumulative probabilities are defined as:

$$199 \quad \gamma_{ij} = \text{Prob}(y_{ij} \geq i) = \sum_i^I \pi_{ij},$$

200 Where (i) is the rank of the response category in question. The measurement equation for the
201 latent variable model can therefore be defined as:

$$202 \quad I_i = \log\left(\frac{\gamma_i}{1-\gamma_i}\right) = \log\left(\frac{\text{Pr}(y_i \geq i)}{\text{Pr}(y_i < i)}\right) = \lambda_i * Z_{in} + u_{in}$$

204

205 **RESULTS**

206

207 **Exploratory analysis**

208

209 The models development early indicated that a global model for all scenarios was unfeasible,
210 due to estimation convergence problems. A review of experiences with such errors in ICLV
211 models revealed that simplifying the model would be the recommended option. Two
212 approaches were found to resolve the estimation problems:

- 213 • The indicators were re-coded in a 3-point Likert scale, by adding up the responses 1-2
214 and 4-5, resulting thus in the following coding for the questionnaire variables: “1 - never
215 or rarely”, “2 - sometimes”, “3 - often or always”. In this way, the number of parameters
216 λ and γ to be estimated, and therefore the degrees of freedom of the models, were
217 substantially reduced; this results in a loss of detail, but may allow for a more robust
218 model.
- 219 • The different scenarios were tested separately, as it was indicated that the different road
220 types and sizes of the choice sets made the estimation more difficult.

221 The results of the two-stage approach were used as a starting point (16); a separate estimation
222 of latent variables on this questionnaire indicated that there are two principal components of
223 pedestrian behavior, one related to ‘risk-taking’ (e.g. questionnaire items ‘I cross diagonally’,
224 ‘I am willing to take any opportunity to cross’, ‘I cross at mid-block in urban roads’, etc.) and
225 one related to ‘pleasure from walking’ (e.g. questionnaire items ‘I walk for health’, ‘I walk for
226 the pleasure of it’ etc.).

227 The models were developed with the Biogeme v2.3 statistical software (24).

228

229 **Models for main urban roads**

230

231 This scenario was the first one tested, as pedestrians’ choice process seems to present the most
232 variability in this type of road. The best performing model was the one shown in Figure 2
233 (bottom left panel), with indicators E1_iii, E1_v and E2_i forming the latent variable “risk”,
234 with pedestrian gender being the risk predictor in the structural equation. More specifically,
235 the model specification is as follows:

236

237 Structural model of the latent variable

238
$$\text{risk} = \text{b_gender} * \text{gender} + \omega$$

239

240 Measurement equations: ordered logit

241
$$I_E1_iii = \lambda_1 * \text{risk} + u_1$$

242
$$I_E1_v = \lambda_2 * \text{risk} + u_2$$

243
$$I_E2_i = \lambda_3 * \text{risk} + u_3$$

244

245 Where:

246
$$I_E1_iii_1 = 1 / [1 + \exp(\lambda_1 * \text{risk} - \gamma_{11})]$$

247
$$I_E1_iii_2 = 1 / [1 + \exp(\lambda_1 * \text{risk} - \gamma_{12})] - 1 / [1 + \exp(\lambda_1 * \text{risk} - \gamma_{11})]$$

248
$$I_E1_iii_3 = 1 - 1 / (1 + \exp(\lambda_1 * \text{risk} - \gamma_{12}))$$

249
$$I_E1_v_1 = 1 / [1 + \exp(\lambda_2 * \text{risk} - \gamma_{21})],$$

250
$$I_E1_v_2 = 1 / [1 + \exp(\lambda_2 * \text{risk} - \gamma_{22})] - 1 / (1 + \exp(\lambda_2 * \text{risk} - \gamma_{21}))]$$

251
$$I_E1_v_3 = 1 - 1 / [1 + \exp(\lambda_2 * \text{risk} - \gamma_{22})]$$

252
$$I_E2_i_1 = 1 / [1 + \exp(\lambda_3 * \text{risk} - \gamma_{31})],$$

253
$$I_E2_i_2 = 1 / [1 + \exp(\lambda_3 * \text{risk} - \gamma_{32})] - 1 / (1 + \exp(\lambda_3 * \text{risk} - \gamma_{31}))]$$

254
$$I_E2_i_3 = 1 - 1 / [1 + \exp(\lambda_3 * \text{risk} - \gamma_{32})]$$

255

256 Choice utility functions

257
$$V1 = \text{ASC1} + \text{B_first} * \text{first} + \text{B_trafflow} * \text{trafflow} + \text{B_risk} * \text{risk}$$

258
$$V2 = \text{ASC2} + \text{B_first} * \text{first}$$

259
$$V3 = \text{ASC3}$$

260

261 Where V1 is the utility of crossing at mid-block, V2 the utility of crossing at junction and V3
 262 the utility of not crossing, ASC are alternative-specific constants, ‘trafflow’ refers to low
 263 traffic conditions, and ‘first’ refers to the first road link of the choice set.

264 The modelling results are presented in Table 4. They can be summarized as follows:

265 • Parameters λ (λ_1 , λ_2 and λ_3) are all statistically significant and positive, indicating that
 266 pedestrians with higher scores on these indicators, i.e. having reported more frequently
 267 the respective risk-taking behavior, have higher “risk”. More specifically, the latent
 268 variable is expressed by the following behaviors:

269 ○ Pedestrians who cross at mid-block on urban roads

270 ○ Pedestrians who cross at mid-block when in a hurry

271 ○ Pedestrians who cross at mid-block between stopped vehicles at congestion.

272 In this case, the self-reported behavior is matched with the observed behavior
 273 Moreover, pedestrians crossing between vehicles when the road is congested is a likely
 274 pattern to be observed on main urban roads.

275 • Pedestrian gender is a significant predictor of the latent variable “risk” (b_gender).
 276 Male pedestrians are found to be more risk-taking.

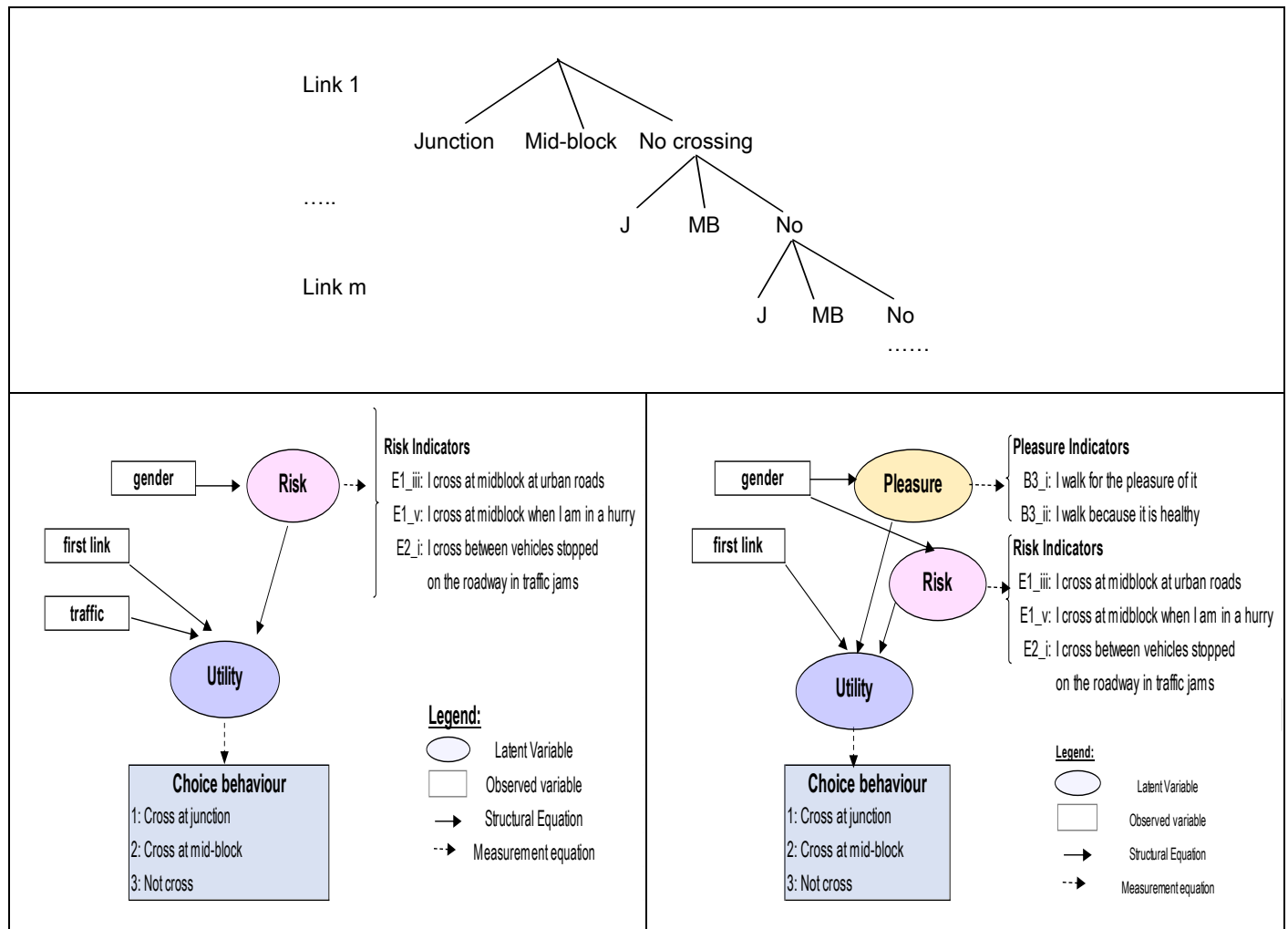
277 • Pedestrians with higher risk-taking (B_risk) appear to be more likely to cross at mid-
 278 block at main urban roads; however the effect is not statistically significant at 90%.

279 • The first road link (B_first) was found to have higher probability of being chosen.

280 • When traffic is low (B_trafflow), mid-block crossing probability increases.

281 An attempt was made, due to the previous results of the two-stage model (16) for the
 282 development of a model with two latent variables, “risk” and “pleasure”. The best performing
 283 model of this combination is shown in Figure 2 (bottom right panel), where indicators B3_i
 284 and B3_ii were used for latent variable “pleasure” and E1_iii, E1_v and E2_i for “risk”, and
 285 pedestrian gender being the risk predictor for both latent variables in the structural equations.

286 The presence of the latent variable “pleasure” seems to improve the significance of the
 287 latent variable “risk”, and the model overall (see Table 4). Nevertheless, the latent variable
 288 ‘pleasure’ was not found significant.
 289
 290



291
 292 **FIGURE 2 Sequential logit model of pedestrian crossing behavior (top panel) - Structure**
 293 **of the ICLV model for main urban roads: Latent variables: risk (bottom left panel) - risk**
 294 **& pleasure (bottom right panel)**
 295
 296
 297
 298
 299
 300

301 **TABLE 4. Parameter estimates of ICLV models for main urban roads - Latent variables:**
 302 **risk (left panel), risk & pleasure (right panel)**
 303

Estimation report	<i>Latent variable: risk</i>			<i>Latent variables: risk & plesure</i>		
Number of parameters:	15			22		
Number o crossings:	184			184		
Init log-likelihood:	-986.670			-3.070.240		
Final log-likelihood:	-607.361			-1.854.286		
Likelihood ratio test:	758.618			2.431.908		
Rho	0.384			0.396		
Rho bar for the init. model:	0.369			0.389		
Diagnostic:	Convergence reached...			Convergence reached...		
Iterations:	36			54		
Estimated parameters						
Name	Value	t-test	p-value	Value	t-test	p-value
ASC1	-2.74	-7.40	0.00	-2.52	-9.44	0.00
ASC2	-1.33	-5.13	0.00	-1.31	-7.23	0.00
B_first	0.466	1.33	0.18	0.427	1.73	0.08
B1_trafficlow	1.54	2.56	0.01	-	-	-
B_risk	0.342	1.13	0.26	-0.410	-1.38	0.17
B_pleasure	-	-	-	-0.248	-0.65	0.52
b_gender	-0.550	-3.12	0.00	0.538	4.88	0.00
b2_gender	-	-	-	-0.375	-2.59	0.01
lamda1	2.78	3.63	0.00	-1.34	-5.58	0.00
gamma11	-2.04	-3.71	0.00	-2.34	-11.31	0.00
gamma12	1.77	3.52	0.00	-0.586	-4.14	0.00
lamda2	3.97	2.20	0.03	-1.89	-6.17	0.00
gamma21	-5.92	-2.46	0.01	-2.73	-11.24	0.00
gamma22	-1.97	-1.94	0.05	-0.713	-4.42	0.00
lamda3	1.38	5.06	0.00	-1.57	-5.86	0.00
gamma31	-2.80	-7.57	0.00	-1.00	-6.57	0.00
gamma32	-0.838	-3.25	0.00	1.25	7.54	0.00
lamda4	-	-	-	-1.65	-5.12	0.00
gamma41	-	-	-	-2.46	-10.35	0.00
gamma42	-	-	-	0.0700	0.43	0.67
lamda5	-	-	-	-1.32	-4.18	0.00
gamma51	-	-	-	-3.03	-10.54	0.00
gamma52	-	-	-	-1.08	-6.98	0.00

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Models for major urban arterials

The structure of the ICLV model developed for major roads is summarized in Figure 3 (top panel). For the “risk” indicators, there were a few that were marginally significant, such as C2_vii, E1_iv and E1_v. The modelling results are presented in Table 5. They can be summarized as follows:

313 • Parameters λ (λ_1 , λ_2 and λ_3) are all statistically significant and positive, indicating that
 314 pedestrians with higher scores on these indicators have higher “risk”. Moreover, the
 315 latent variable is expressed by the following behaviors:

- 316 ○ Pedestrians who are willing to take any opportunity to cross
- 317 ○ Pedestrians who cross at mid-block when in a hurry
- 318 ○ Pedestrians who cross at mid-block in residential areas

319 It is somewhat surprising that the indicator for crossing mid-block in residential areas
 320 contributes to the latent variable for major roads; one might expect a stronger role of
 321 the “crossing at major urban arterials” indicator. This may be interpreted in two ways:
 322 first, pedestrians are less likely to declare crossing at mid-block in major urban arterials,
 323 even if they do so under certain conditions; and second, pedestrians who cross
 324 frequently at mid-block in residential areas may be more likely to cross at mid-block in
 325 other conditions as well.

326 In this case, the γ parameters were assigned fixed values in order for the model to
 327 converge.

- 328 • Pedestrian age is a significant predictor of the latent variable “risk” (b_{age}). Pedestrians
 329 older than 25 (i.e. mostly 25-45) years are found to be more risk-taking compared to
 330 pedestrians younger than 25 years.
- 331 • Pedestrians with higher risk-taking (B_{risk}) are more likely to cross at mid-block at
 332 major roads; although mid-block crossing was observed very rarely in this scenario
 333 (only 7 out of 203 crossings), it was strongly associated with high-risk reported
 334 behavior.
- 335 • The first road link (B_{first}) was found to have lower probability of being chosen in this
 336 scenario.
- 337 • No effect of traffic was found on this crossing scenario, and this may be attributed to
 338 the increased traffic and the high number of lanes of this type of road, leading
 339 pedestrians to less variation in their crossing behavior.

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341 **Models for secondary urban roads**

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343 The structure of the ICLV model developed for secondary roads is summarized in Figure 3
 344 (middle panel). The best performing model was one with indicators E1_iii, E1_i forming the
 345 latent variable “risk”, with pedestrian age and gender being the risk predictors in the structural
 346 equation.

347 The modelling results are also presented in Table 5. They can be summarized as follows:

- 348 • Parameters λ (λ_1 , λ_2) are all statistically significant and positive. The latent variable is
 349 expressed by the following behaviors:
 - 350 ○ Pedestrians who cross at mid-block on urban roads
 - 351 ○ Pedestrians who cross diagonally.

352 In this case, the self-reported behavior is matched with the observed behavior.
 353 Moreover, pedestrians crossing diagonally are obviously more likely to cross at mid-
 354 block, especially on a secondary road.

- 355 • Pedestrian gender is not a significant predictor of the latent variable “risk” (b_{gender}).
- 356 • Pedestrian age is a significant predictor of the latent variable “risk”, and younger
 357 pedestrians (<25 years) are more likely to exhibit risk-taking behavior (b_{age}) than
 358 middle aged pedestrians (25-45 years).
- 359 • The latent variable risk-taking (B_{risk}) is not statistically significant in the choice
 360 model. This is not surprising, as on secondary roads the road and traffic environment is
 361 not very demanding, and conditions for risk-taking behavior may be less present.

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- The first road link (B_first) was found to have higher probability of being chosen in this scenario.
 - When traffic is low (B_trafficlow), midblock crossing probability decreases - compared, in this case, to the conditions of empty traffic.

367 **Models for residential areas**

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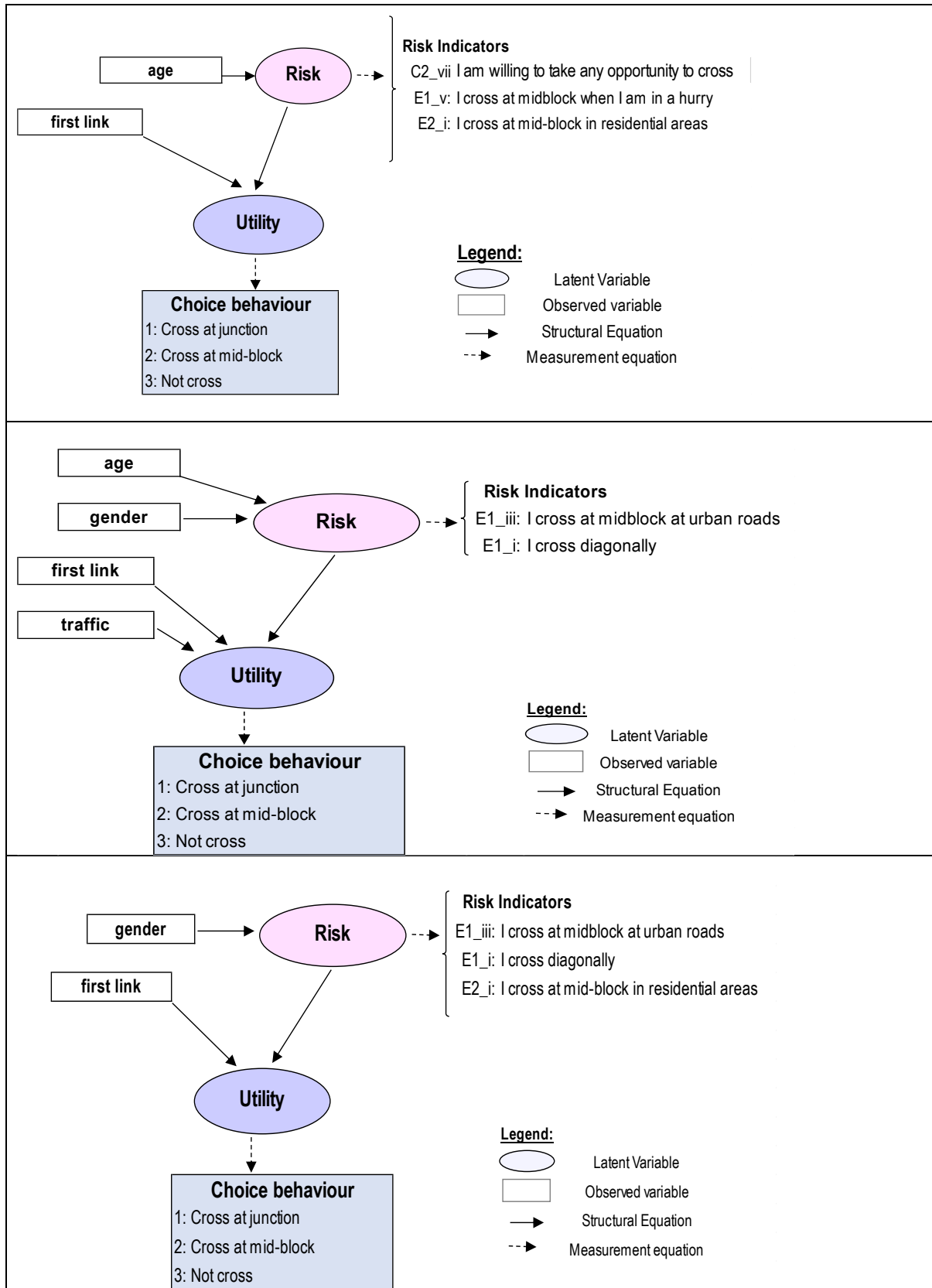
369 The structure of the ICLV model for residential roads is presented in Figure 3 (bottom panel).
370 The various combinations examined resulted in a latent variable with three indicators, namely
371 E1_i, E1_iii and E2_i. The modelling results are presented in Table 5:

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- Parameters λ (λ_1 , λ_2 and λ_3) are all statistically significant and positive. More specifically, the latent variable is expressed by the following behaviors:
 - Pedestrians who cross at mid-block on urban roads
 - Pedestrians who cross diagonally
 - Pedestrians who cross at mid-block on residential roads

377 In this case as well, the self-reported behavior is matched with the observed behavior.
378 Moreover, pedestrians crossing diagonally are obviously more likely to cross at mid-
379 block.

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- Pedestrian gender is a significant predictor of the latent variable “risk” (b_gender).
 - The latent variable risk-taking (B_risk) is statistically significant in the choice model. On residential roads the road and traffic environment is not at all demanding, and conditions for ‘optimizing’ behavior (i.e. mid-block crossing, diagonal crossing) may be a common practice.
 - The first road link (B_first) was found to have higher probability of being chosen in this scenario.
 - No effect of traffic on pedestrian crossing behavior was found in this type of road network, which was expected.

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FIGURE 3 Structure of the ICLV models for: a) major urban arterials - Latent variable: risk (top panel), b) secondary roads - Latent variable: risk (middle panel), c) residential roads - Latent variable: risk (bottom panel)

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400**TABLE 5 Results of ICLV model for a) major urban arterials - Latent variable: risk (left panel), b) secondary roads - Latent variable: risk (middle panel), c) residential roads - Latent variable: risk (right panel)**

Estimation report	<i>Major roads</i>			<i>Secondary roads</i>			<i>Residential roads</i>		
Number of parameters:	8			13			14		
Number of crossings:	203			263			239		
Init log-likelihood:	-1.073.024			-965.574			-1.164.738		
Final log-likelihood:	-821.159			-724.802			-894.889		
Likelihood ratio test	503.730			481.544			539.700		
Rho	0.235			0.249			0.232		
Rho bar	0.227			0.236			0.220		
Diagnostic:	Convergence reached...			Convergence reached...			Convergence reached...		
Iterations:	220			35			32		
Estimated parameters									
Name	Value	t-test	p-value	Value	t-test	p-value	Value	t-test	p-value
ASC1	2.33	0.10	0.92	-1.60	-5.09	0.00	-1.91	-5.69	0.00
B_first	-6.54	-0.27	0.79	0.364	1.28	0.20	0.884	2.41	0.02
B1_trafficlow	-	-	-	-1.38	-2.88	0.00	-	-	-
B_risk	1.10	1.91	0.06	0.0189	0.09	0.93	0.588	2.77	0.01
b_gender	-	-	-	0.0915	0.51	0.61	-0.516	-2.80	0.01
b_age	1.40	8.09	0.00	0.960	4.63	0.00	-	-	-
ASC2	7.00	0.29	0.77	-1.70	-7.05	0.00	-1.29	-5.72	0.00
lamda1	0.750	6.25	0.00	2.65	1.69	0.09	1.40	4.32	0.00
gamma11	0.5	-	-	0.827	1.63	0.10	-1.05	-4.20	0.00
gamma12	1,00	-	-	4.04	2.31	0.02	1.26	4.94	0.00
lamda2	2.15	6.89	0.00	0.921	4.25	0.00	1.61	3.92	0.00
gamma21	0.5	-	-	-0.153	-0.69	0.49	-2.53	-5.23	0.00
gamma22	1,00	-	-	1.83	5.65	0.00	-0.757	-2.43	0.02
lamda3	1.99	6.53	0.00	-	-	-	1.34	4.26	0.00
gamma31	0.5	-	-	-	-	-	-0.581	-2.66	0.01
gamma32	1,00	-	-	-	-	-	1.47	5.56	0.00

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405**DISCUSSION**

Overall, the four ICLV models estimated in the present research largely confirm the research hypotheses (16) as per the effects of road, traffic and human factors of pedestrian crossing behavior. The effect of traffic volume was non significant on major roads and on minor / residential roads, but was significant on main and secondary roads. The effect of risk-taking was significant on major and minor roads, and marginally significant or non-significant on main and secondary roads. Overall, “risk-taking” is a key factor for crossing at mid-block when traffic is high, and “trip optimization” is a key factor for crossing at mid-block when traffic is low.

In none of the ICLV models was ‘pleasure’ a significant latent variable. This finding was somewhat surprising, and may be partly attributed to the specific trip not being

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416 representative of the usual walking motivations of those participants who often walk for
417 pleasure.

418 Another key finding is that, the research hypotheses on the road and traffic factors of
419 pedestrian behavior were largely confirmed, but the research hypotheses on human factors of
420 pedestrian crossing behavior were not fully confirmed. In particular, it was assumed that there
421 were five factors of pedestrian behavior, each one corresponding to one section of the survey
422 questionnaire. However, the survey responses do not confirm this structure, suggesting that the
423 underlying dimensions are in fact few, with the 'risk-taking' dimension being the dominant
424 one.

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426 **CONCLUSION**

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428 The results of the ICLV models indicate that this family of models is very pertinent and
429 useful for addressing the behavioral aspects of pedestrian trips in urban areas. It was clearly
430 indicated that human factors may be important additional predictors of pedestrian behavior.

431 On the basis of the integrated models tested in this research, as well as the two-stage
432 models tested in previous stages of this research (16), it appears that both approaches can be
433 meaningful: the measurement error in the two-stage approach appears negligible, as the
434 results of both approaches were similar as per the sign, the magnitude and the statistical
435 significance of human factors. The ICLV approach is theoretically sounder; however, it is a
436 computationally demanding technique and the estimation of a global model was not possible.
437 On the other hand, the latent variables estimated by the ICLV models are clearly defined and
438 more easily interpreted.

439 In general, it would be recommended to implement more pedestrian surveys
440 combining field observations and questionnaires. The present sample is not representative of
441 age groups, and the inclusion of older pedestrians in the sample in a future research might
442 reveal additional effects of human factors on crossing behavior. Moreover, the sample size of
443 this field survey is marginally adequate for a structural equation approach for latent variables.
444 Measurements may not be stable and replicable at this sample size, and although the model
445 was simplified to enhance validity, more data would be required to generalize the results to
446 different settings. The present research also has limitations due to the fact that participants
447 knew that they were being observed, and the role of their usual travel motivations could not
448 be captured. An alternative approach would be to capture crossing behavior of people who
449 are not aware that they are being observed, and then follow up with them to participate in a
450 simplified survey. In this case, however, the researcher would not be able to control for their
451 route choice.

452 The proposed methodology and results need further development, more data and
453 validation before they can be used for practical applications. The next steps of the research
454 should address in particular the model's validation, internal (e.g. with a small part of the
455 existing dataset left out in the model development and used for validation) and external (i.e.
456 by means of new data collected). This analysis allow tackling the question of using such
457 models for prediction.

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459 **ACKNOWLEDGEMENTS**

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461 This paper is based on a research project implemented within the framework of the Action
462 «Supporting Postdoctoral Researchers» of the Operational Program "Education and Lifelong
463 Learning" (Action's Beneficiary: General Secretariat for Research and Technology), co-
464 financed by the European Social Fund (ESF) and the Greek State.

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