## Combining traffic simulation and driving simulator analyses for Advanced Cruise Control system impact identification

George Yannis John Golias National Technical University of Athens Constantinos Antoniou Massachusetts Institute of Technology

### Abstract

The objective of this research is to combine microscopic traffic simulation and driving simulator pilot tests of vehicles equipped with Advanced Cruise Control (ACC) systems, aiming to identify traffic and safety impact of the introduction of this technology. The relevant outputs of two microscopic traffic simulation and driving simulator experiments were analysed and the similarities between their experimental designs were identified. Relevant outputs were crosstabulated and analysed, and qualitative results were extracted. Indicators selected for the purposes of this research include average speed, minimum and desired headways, and Time-To-Collision (TTC). The analysis indicates that the impact of ACC on the average speed is minimal, while headways and time-to-collision distributions are decreased. While these findings indicate positive traffic impacts, shorter headways and TTC values could have negative safety implications. Our findings have resulted in conclusions for the future development of ACC systems but also illustrated the usefulness for extracting a more complete assessment through the combination of traffic simulation results with respective results from driving simulators.

## Introduction

- This research has been undertaken within the scope of the ADVISORS European Union project
- Results from two methodologies:
  - microscopic traffic simulation and
  - driving simulator experiments
  - were combined
- While the two efforts had different objectives, there is sufficient overlap to support this analysis

# Microscopic traffic simulation models

- SIMONE (Minderhoud, 1999, and Minderhoud and Bovy, 1999)
  – TRAIL/University of Delft
- SISTM (Stevens et al., 2000)
  - Transport Research Laboratory (TRL)

# Driving simulator tests

- Performed by the Swedish National Road and Transport Research Institute (VTI)
  - Detailed description available in Tornros et al., 2002

# Scope of the analysis

- Adaptive Cruise Control (ACC) was selected for the analysis
- Motorway sections were modeled
- Driving simulator: drivers with various experience levels were used
- The following indicators were selected:
  - Average speed
  - Minimum and desired headways
  - Time-To-Collision (TTC)

### Advanced Cruise Control (ACC) Functional Characteristics

	Microscopic traffic	Microscopic traffic	Driving simulator
Characteristic	simulation models	simulation models	
	SIMONE	SISTM	VTI
Speed range	30 to 170	0 to 142	50 to 140
(km/h)			
Acceleration	0 to 4	0 to 0.28	0 to 1
range (m/s²)			
Deceleration	0 to 2.5	0 to 1.25	0 to 2.5
range (m/s²)			
Minimum time	1 to 2.5 (based on	1.5	0.8
headway (s)	control settings)	2.0	1.0
			1.5
Penetration	0%	0%	(indirect assessment)
rates	5%	10%	
	10%	1070	
	25%	50%	
	50%	90%	
	100%	5070	

### Microscopic simulation sample results



Critical speed as a function of ACC penetration (SIMONE microscopic simulator).



Headway distribution by lane (top: no ACC, bottom: 25% ACC penetration, SIMONE microscopic simulator)

### Summary of results (quantitative)

	Microscopic traffic	Microscopic traffic	Driving simulator
Measure	simulations	simulations	
	SIMONE	SISTM	VTI
Average speed	Up to 10% increase in	Up to 7% increase	No change
	critical speed		
Headway	ACC leads in a narrower	Small increase (1% - 2%)	Significant decrease in average
distribution	distribution (around the	for low flows, 2%-5%	distance headway from 51m to 31 m.
	system-dictated headway)	decrease otherwise.	
			Average preferred headway: 1.4s-
			2.8s (without ACC) and 1.5s-2.5s
			(with ACC)
Time-to-collision	50% decrease in	Up to 35% decrease in	Decreases in large values (e.g. from
	"dangerous" values, i.e.	proportion of TTC less	17s to 10s), and increases in other
	less than 1.5s	than 10s	cases (e.g. from 2.35s to 2.52s)
	15-20% increase in	Up to 15% decrease in	
	"uncomfortable" values,	proportion of TTC less	
	i.e. below 3s	than 1s	

# Summary of results (qualitative)

Measure	Microscopic traffic simulations SIMONE	Microscopic traffic simulations SISTM	Driving simulator VTI
Average speed	0, (+)	0, +	0
Headway distribution	+	+	+
Time-to-collision	+	+	+

# Conclusions

- The two methodologies have different properties, advantages and disadvantages
  - However, under certain conditions, their outputs can be compared and analyzed together
- Impact of ACC increases monotonically with penetration level
  - No "critical" penetration level
  - Positive traffic impact
  - Potentially negative safety implications (shorter headways and TTC values)

## Directions for future research

- Investigation of more scenarios (e.g. ADA systems and network characteristics)
  - Can the findings be generalized to other ADA systems?
  - Sensitivity analysis/robustness of these findings
  - To what extent are the discrepancies due to differences in the methodologies?
- Use of driving simulator findings for calibration of behavioral models in microscopic simulators
  - For example, behavior of drivers using ADAS, which may not yet be widely available in vehicles (therefore this behavior cannot be directly observed)

#### Author contact information

George Yannis

National Technical University of Athens, 5, Iroon Polytechniou st., GR-157 73 Zografou, Athens, Greece Tel:+301-7721326, Fax: +301-7721327, email: geyannis@central.ntua.gr

John Golias National Technical University of Athens, 5, Iroon Polytechniou st., GR-157 73 Zografou, Athens, Greece Tel:+301-7721276, Fax: +301-7721327, email: igolias@central.ntua.gr

Constantinos Antoniou Massachusetts Institute of Technology, 77 Massachusetts Ave., NE20-208, Cambridge, MA 02139 Tel: 617-2521113, Fax: 617-2521130, email: costas@mit.edu