



Establishing the relationship between crashes and unsafe driver behaviors in motorway segments

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INTRODUCTION

- Crash-based safety analysis suffers from several limitations (e.g., unreliable crash data)
- Surrogate safety analysis stands as an alternative approach.
- It remains unclear how various metrics that describe **unsafe driving** relate to crash occurrence.

OBJECTIVES

This work aims to address existing research gaps by investigating the relationship between crashes and three unsafe driver behaviors: **1. speeding**, **2. harsh braking** and **3. harsh acceleration**. The outcome of this work will be a step towards the establishment of proactive safety assessment methods.

DATA

The analysis was conducted for Olympia Odos motorway, (~200km) for which relevant data were available.

- Road data:** horizontal curve radius, inside and outside shoulder widths, outside clearance, lane width, median width, barrier type, and interchange design characteristics
- Crash data (2017-2020)**
- AADT data (2017-2020)**
- Driver telematics data:** 2019 and 2020 trip data with a total of ~1.3 million trips

Figure 1: Crash frequency per year

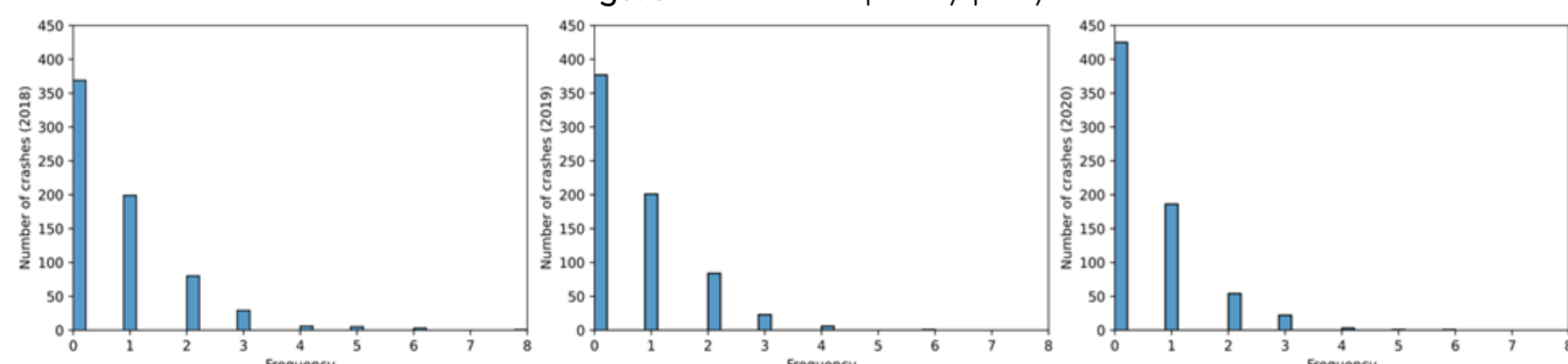


Table 1: Summary statistics for the representative dataset provided by OSeven.

	2019 (6 months)			2020 (12 months)		
	Harsh acceleration events	Harsh braking events	Speeding events	Harsh acceleration events	Harsh braking events	Speeding events
Mean	1.42	1.56	1.26	1.53	1.69	1.27
St. deviation	13.63	11.89	9.15	11.67	10.85	10.11
Variance	185.83	141.28	83.72	136.23	117.69	102.21

METHODOLOGY

Crash prediction models were developed to model the relationship between crashes and unsafe driver events. It is assumed that the number of crashes per motorway segment follows the Poisson distribution.

RESULTS

Table 2: Crash prediction model with harsh acceleration events

Variable	Coefficient	St. Error	z	P> z	[0.025	0.975]
Intercept	-7.0100	1.337	-5.245	0.000	-9.630	-4.390
ln(AADT)	0.7740	0.143	5.415	0.000	0.494	1.054
ln(length)	0.9291	0.273	3.402	0.001	0.394	1.464
Average HA	20.1427	8.826	2.257	0.023	2.647	37.638

Table 3: Crash prediction model with harsh braking events

Variable	Coefficient	St. Error	z	P> z	[0.025	0.975]
Intercept	-7.4137	1.335	-5.552	0.000	-10.031	-4.796
ln(AADT)	0.8134	0.143	5.690	0.000	0.533	1.094
ln(length)	0.8598	0.266	3.234	0.001	0.339	1.381
Average HB	18.4454	12.930	1.426	0.154	-6.899	43.788

Table 4: Crash prediction model with harsh speeding events

Variable	Coefficient	St. Error	z	P> z	[0.025	0.975]
Intercept	-7.2976	1.999	-3.651	0.000	-11.215	-3.380
ln(AADT)	0.8014	0.204	3.933	0.000	0.402	1.201
ln(length)	0.8085	0.262	3.082	0.002	0.294	1.323
Average Speeding	0.0289	0.646	0.045	0.964	-1.237	1.295

CONCLUSIONS

The conclusions drawn from the current research can serve as the **base for developing similar** models to further explore the relationship between unsafe driver events and crash occurrence. Future research should explore how disaggregate driver telematics data can be used instead of aggregated one.

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