





11th INTERNATIONAL CONGRESS on TRANSPORTATION RESEARCH Clean and Accessible to All Multimodal Transport Heraklion, Crete, September 20th - 22nd 2023

Modelling the inter-relationship among task complexity, coping capacity and crash risk

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Together with:

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The i-DREAMS project

- > 13 Project partners:
 - <u>National Technical University of Athens</u>

<u>Universiteit Hasselt</u>, <u>Loughborough University</u>, <u>Technische</u> <u>Universität München</u>, <u>Kuratorium für Verkehrssicherheit</u>, <u>Delft University of Technology</u>, <u>University of Maribor</u>, <u>OSeven</u> <u>Telematics</u>, <u>DriveSimSolutions</u>, <u>CardioID Technologies</u>, <u>European Transport Safety Council</u>, <u>POLIS Network</u>, <u>Barraqueiro Transportes S.A.</u>

- > Duration of the project:
 - 48 months (May 2019 April 2023)
- **Framework Program**:
 - <u>Horizon 2020</u> The EU Union Framework Programme for Research and Innovation - Mobility for Growth





Introduction

Human behaviour plays a critical role in road safety

- Factors such as speeding, distraction, aggressive or impaired driving and non-compliance with traffic regulations can increase the crash risk
- Poorly designed roads, inadequate signage, absence of pedestrian crossings, lack of proper lighting and insufficient maintenance have a direct impact on road safety
- Environmental conditions and safety features of vehicles can also contribute to crashes and injuries

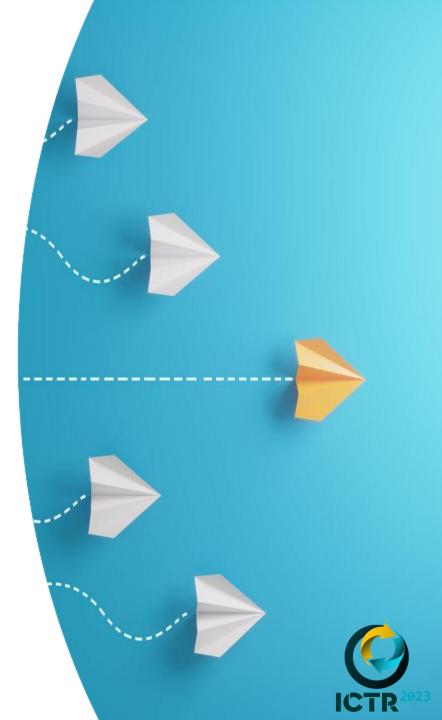




Objectives

- Identification of the most critical indicators of risk from both the task complexity and the coping capacity (vehicle and operator state) side
- Examination of the impact of vehicle, operator and context characteristics on risk under several conditions and phases
- Development of an integrated model for understanding the effect of driver-vehicleenvironment interaction with risk
- Comparison of the performance of such model on different countries





Data Description

- Task complexity relates to the current status of the real world context in which a vehicle is being operated:
 - road layout (i.e. highway, rural, urban)
 - time and location
 - traffic volumes (i.e. high, medium, low)
 - weather conditions
- Coping capacity is dependent upon two underlying factors and it consists of several aspects:
 - vehicle state (e.g. technical specifications, actuators & admitted actions, current status)
 - operator state (e.g. mental state, behaviour, competencies, personality, sociodemographic profile)

Task complexity	Coping capacity – vehicle state	Coping c operat	Risk		
Car wipers Vehicle age		Distance	Inter Beat Interval	Headway map levels	
Car high beam	First vehicle registration	Duration	Headway	Speeding map levels	
Time indicator	Fuel type	Average speed	Overtaking	Overtaking map levels	
Distance	Engine Cubic Centimeters	Harsh acceleration/ braking	Fatigue	Fatigue map levels	
Duration	Engine Horsepower (HP)	Forward collision warning (FCW)	Gender	Harsh acceleration	
Month	Gearbox	Pedestrian collision warning (PCW)	Age	Harsh braking	
Day of the week	Vehicle brand	Lane departure warning (LDW)	Educational level	Vehicle control events	



Experiment Phases

Phase 1 (Baseline)	 Intervention: No Description: a reference period after the installation of the i-DREAMS system in order to monitor driving behavior without interventions Duration: 4 weeks
Phase 2	 Intervention: Real-time Description: a monitoring period during which only in vehicle real-time warnings provided using adaptive ADAS Duration: 4 weeks
Phase 3	 Intervention: Real-time + Post-trip Description: a monitoring period during which in addition to real-time in vehicle warnings, drivers received feedback on their driving performance through the app Duration: 4 weeks
Phase 4	 Intervention: Real-time + Post-trip + Gamification Description: a monitoring period during which in vehicle real-time interventions were active along with feedback but at the same time gamification elements were also active Duration: 6 weeks

ICTR²⁰²³



Methodological Overview

- A naturalistic driving experiment was carried out involving 120 car drivers from Belgium, UK and Germany and a large database consisting of 26,900 trips was collected and analyzed
- Questionnaire data were also collected both before and after the field trials
- Explanatory analyses such as Generalized Linear Models (GLMs) were performed
- Structural Equation Model (SEMs) were also developed in order to identify the relationship between observed (i.e. number of speeding events) and latent or unobserved variables (i.e. crash risk)





GLM Results

- GLMs were employed to investigate the relationship of the key performance indicator of speeding for Belgian, UK and German car drivers
- In Belgium, the indicators of task complexity, such as time indicator and wipers were positively correlated with speeding which means that higher speeding events occur at night compared to during the day
- In UK, the indicators of coping capacity, such as FCW and LDW) were positively correlated with speeding, while gender was a significant variable showing that male drivers are more prone to exceed the speed limits
- In Germany, the indicators of coping capacity vehicle state such as fuel type and vehicle age were positively correlated with speeding

Variables	Est	imate		SE	z-value		Pr(z)	VIF			
Belgium											
(Intercept)		3.668		0.043	85.768	85.768		-			
Time indicator	0.	0.908		0.078	11.683	11.683		1.882			
Weather	0.	0.009		217×10 ⁻⁴	20.952		< .001	1.228			
High beam - Off		-0.018)62×10 ⁻⁴	-25.286	-25.286		1.470			
Harsh acceleration	eleration 2		0.181		14.689		< .001	1.013			
Distance -6.12		8×10-4	7.2	273×10 ⁻⁵	-8.426		< .001	1.678			
UK											
(Intercept)		-3.82		0.014	-274.62	0	< .001	-			
Duration		4.672×10 ⁻⁵		7.877×10	⁻⁷ 59.317	'	< .001	1.058			
Harsh acceleration		-0.187		0.012	-15.37	7	< .001	1.014			
Weather		-0.273		0.023	-11.713	}	< .001	1.008			
Forward collision warning		10.603		2.479	4.276		< .001	1.001			
Lane departure war	ning	0.357		0.014	25.348	25.348		1.026			
Distance		0.002		1.876×10 ⁻	-5 117.628	117.628		1.072			
Gender - Male		0.373		0.012	31.757	,	< .001	1.056			
			Ge	rmany							
(Intercept)	1.1	05		0.057	19.549		< .001	-			
Duration	0.0	03	3.4	414×10 ⁻⁵	73.366		< .001	1.262			
Distance	5.735	×10 ⁻⁴	3.723×10 ⁻⁵		15.404		< .001	1.029			
Harsh acceleration	1.282	1.282×10 ⁻⁴		974×10 ⁻⁶	64.951		< .001	1.222			
Fuel type - Petrol	0.2	219	0.010		21.446		< .001	1.328			
Vehicle age	3.162	×10 ⁻⁵	3.340×10 ⁻⁶		9.469		< .001	1.277			
Gender - Female	-0.275		0.021		-13.025		< .001	1.256			
Drowsiness	1.009×10 ⁻⁵		2.656×10 ⁻⁶		3.800		< .001	1.113			
Time indicator	8.547	×10 ⁻⁵	1.9	025×10 ⁻⁶	44.405		< .001	1.080			
High beam - On	0.8	817		0.059	13.963		< .001	1.073			

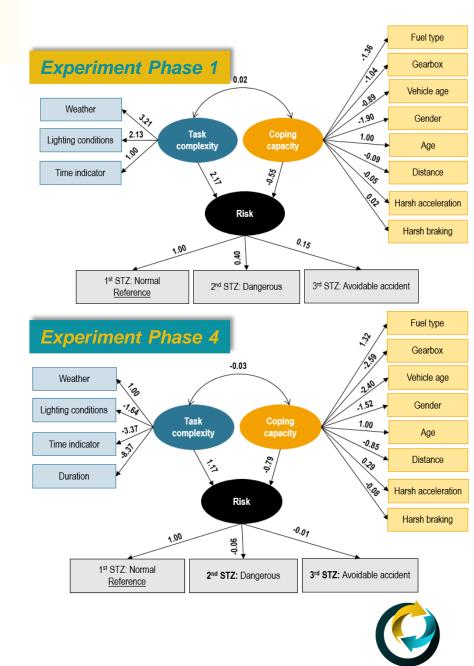




SEM Results

- The latent variable risk was measured by means of the STZ levels for speeding, headway, overtaking and fatigue
- The positive correlation of task complexity and coping capacity implied that drivers' coping capacity increased as the complexity of driving task increases
- This finding may be a sign of risk compensating behavior of drivers when the complexity of driving task is high, validating the assumption that risk (or its' inverse, the normal driving) is an outcome of the interaction between the two variables in addition to their separate effect
- A positive correlation of risk with the STZ indicators was identified in phase 1, while a negative correlation was found in phase 4 which showed that the latent variable risk could in fact be representing an inverse of risk, more like a normal driving





Discussion

- Higher task complexity was associated with an increased crash risk. Drivers could probably become overwhelmed by the demands of complex tasks, leading to reduced attention to the road and other traffic participants
- Conversely, drivers with limited coping capacity may struggle to effectively manage complex tasks, leading to higher crash risk. Reduced coping capacity can manifest as slower reaction times, impaired judgment, and difficulties in prioritizing information
- The positive correlation of task complexity and coping capacity implied that drivers' coping capacity increased as the complexity of driving task increases. This means that drivers, when faced with difficult conditions, tend to regulate well their capacity to apprehend potential difficulties, while driving





Conclusions

- Understanding and modeling the inter-relationship among task complexity, coping capacity and crash risk is vital for developing targeted interventions and countermeasures to enhance traffic safety and reduce crash risk
- This includes improving road infrastructure, implementing appropriate signage and road markings, educating drivers about the impact of task complexity on their performance, and promoting the development of coping strategies to manage complex driving situations
- Technological advancements in vehicle automation and driver assistance systems can play a role in mitigating crash risk by reducing the cognitive load associated with complex tasks and providing support to drivers in challenging conditions









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Loughborough