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Exploitation of naturalistic driving data to estimate crash risk through machine learning

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Introduction

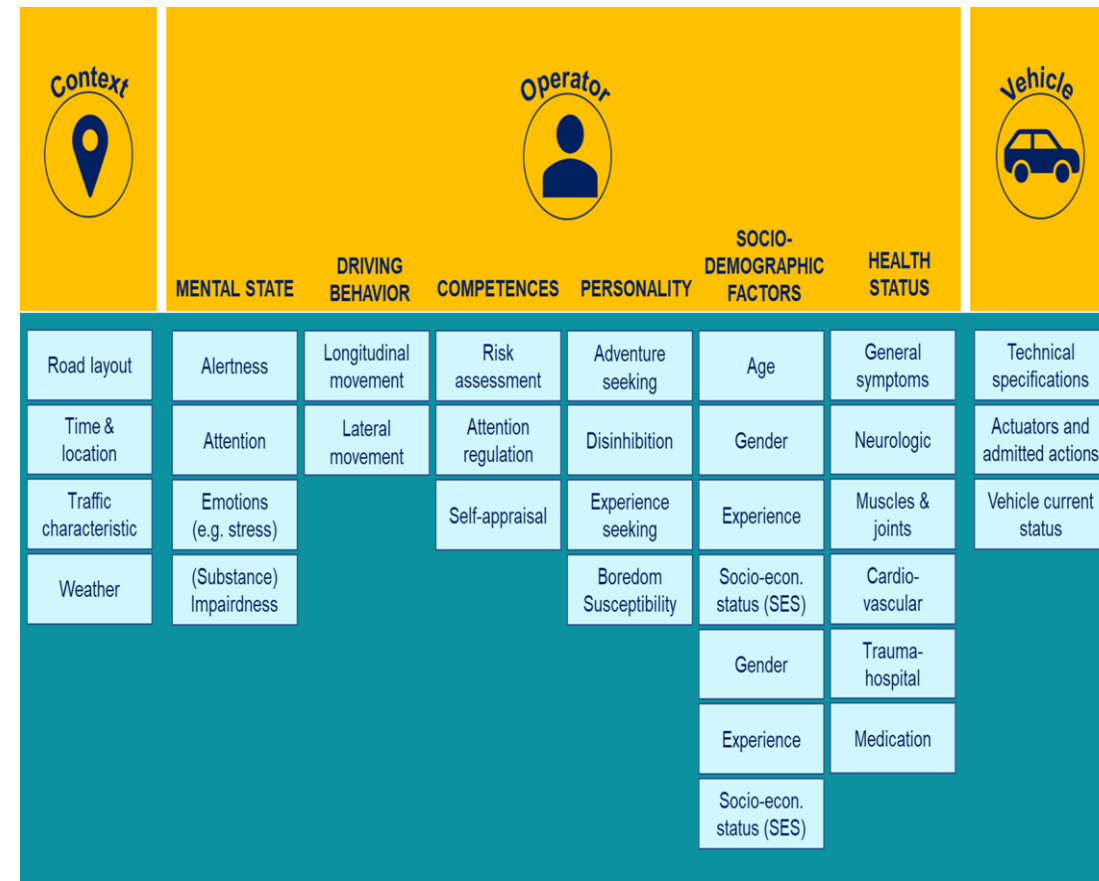


- In modern society and reality, **road transport** consists an important part of people's daily lives, as they use it for all their activities during the course of a day
- With the ever-increasing need for daily traffic movements, **road crashes** are also increasing, bringing to light the prominent issue of road safety
- Annual **road traffic fatalities** amount to 1.19 million and are the leading **cause of death** in people aged 5-29 years



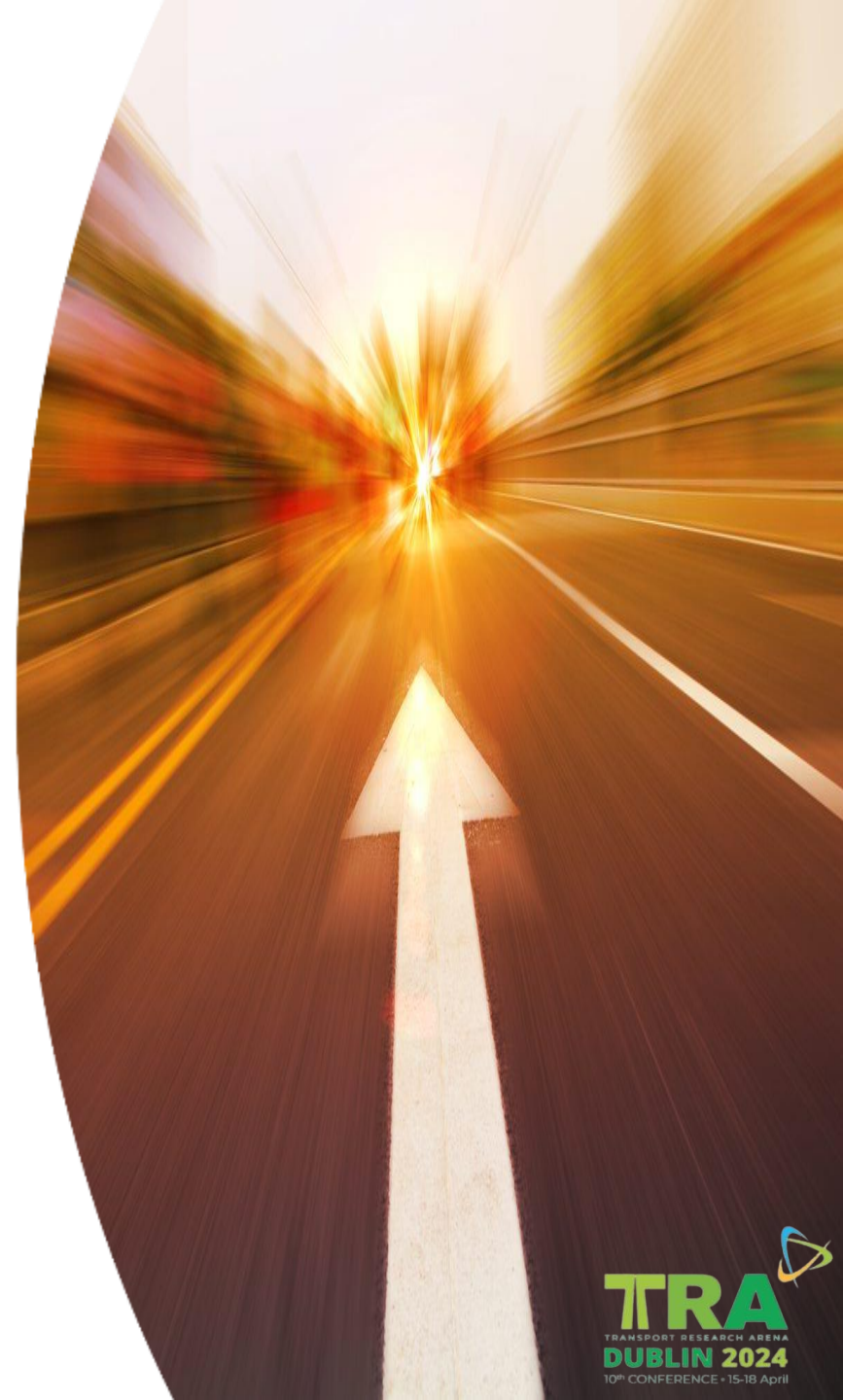
Data Description

- **Task complexity** relates to the current status of the real world context in which a **vehicle** is being operated:
 - ✓ road layout (i.e. highway, rural, urban)
 - ✓ time and location
 - ✓ traffic volumes (i.e. high, medium, low)
 - ✓ weather conditions
- **Coping capacity** is dependent upon two underlying factors and it consists of several aspects of **vehicle state**:
 - ✓ technical specifications
 - ✓ current vehicle status
- and **operator state**:
 - ✓ mental state
 - ✓ driving behavior
 - ✓ competencies
 - ✓ personality
 - ✓ sociodemographic profile
 - ✓ health status



Objectives

- Identification of the most **critical indicators of risk** from both the task complexity and the coping capacity (vehicle and operator state) side
- Explanatory **variables of risk**, such as time headway, distance traveled, speed, time of the day (lighting indicators), or weather conditions were assessed
- Development of **SEMs (Structural Equation Models)** for estimating the effect of different factors (speeding, harsh braking etc.) in crash risk



Methodology

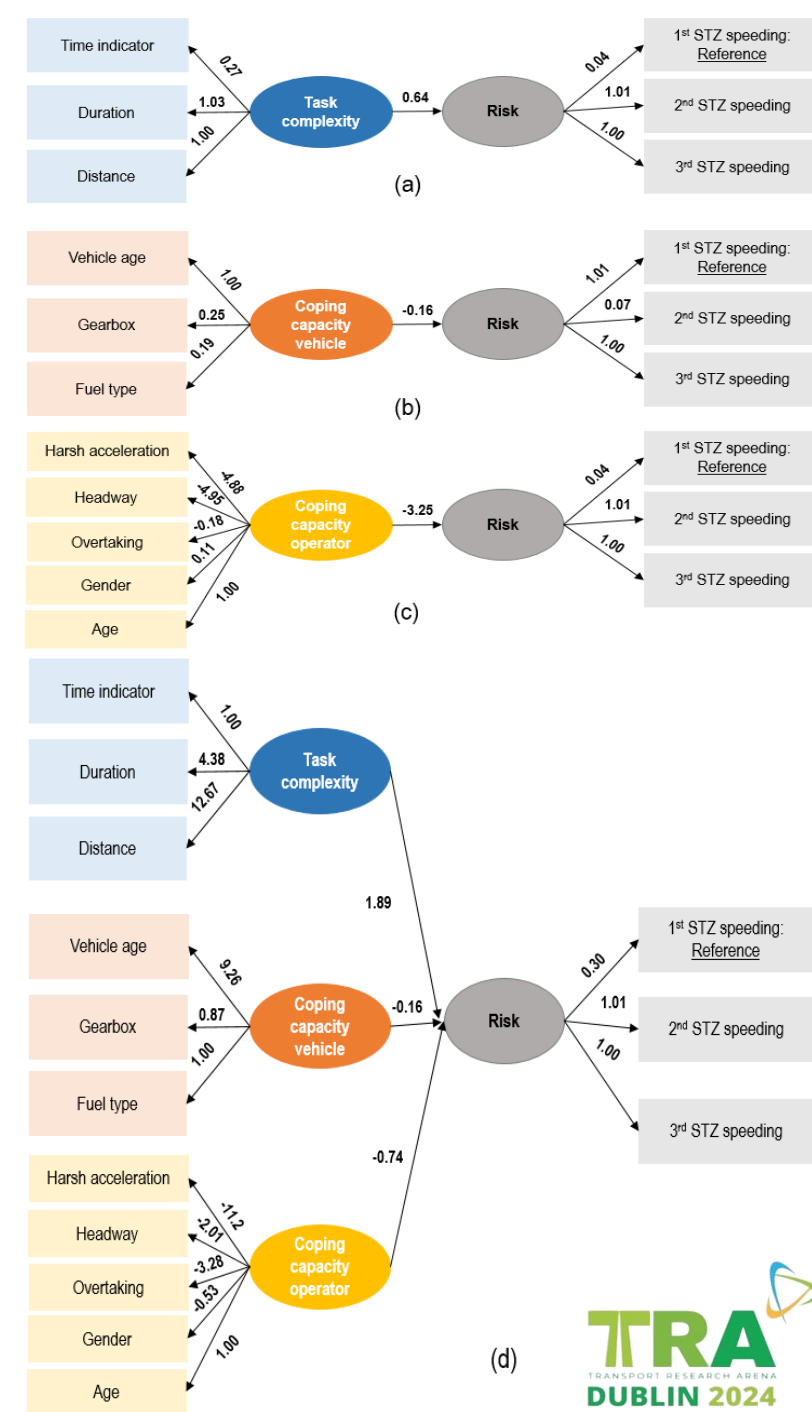


- A **naturalistic driving experiment** was carried out for 4 months, involving 30 car drivers from the UK and a large database was collected and analyzed
- **Structural Equation Model (SEMs)** were developed in order to identify the relationship between observed (i.e. number of speeding or harsh braking events) and latent or unobserved variables (i.e. task complexity)
- The results of the models were evaluated by satisfying the following **statistical tests**: $p\text{-value} < 0.001$, $CFI > 0.90$, $TLI > 0.90$, $SRMR < 0.05$, $RMSEA < 0.05$
- Through tests carried out, the **dependent variables** for which the most significant results were obtained, were speeding and harsh braking



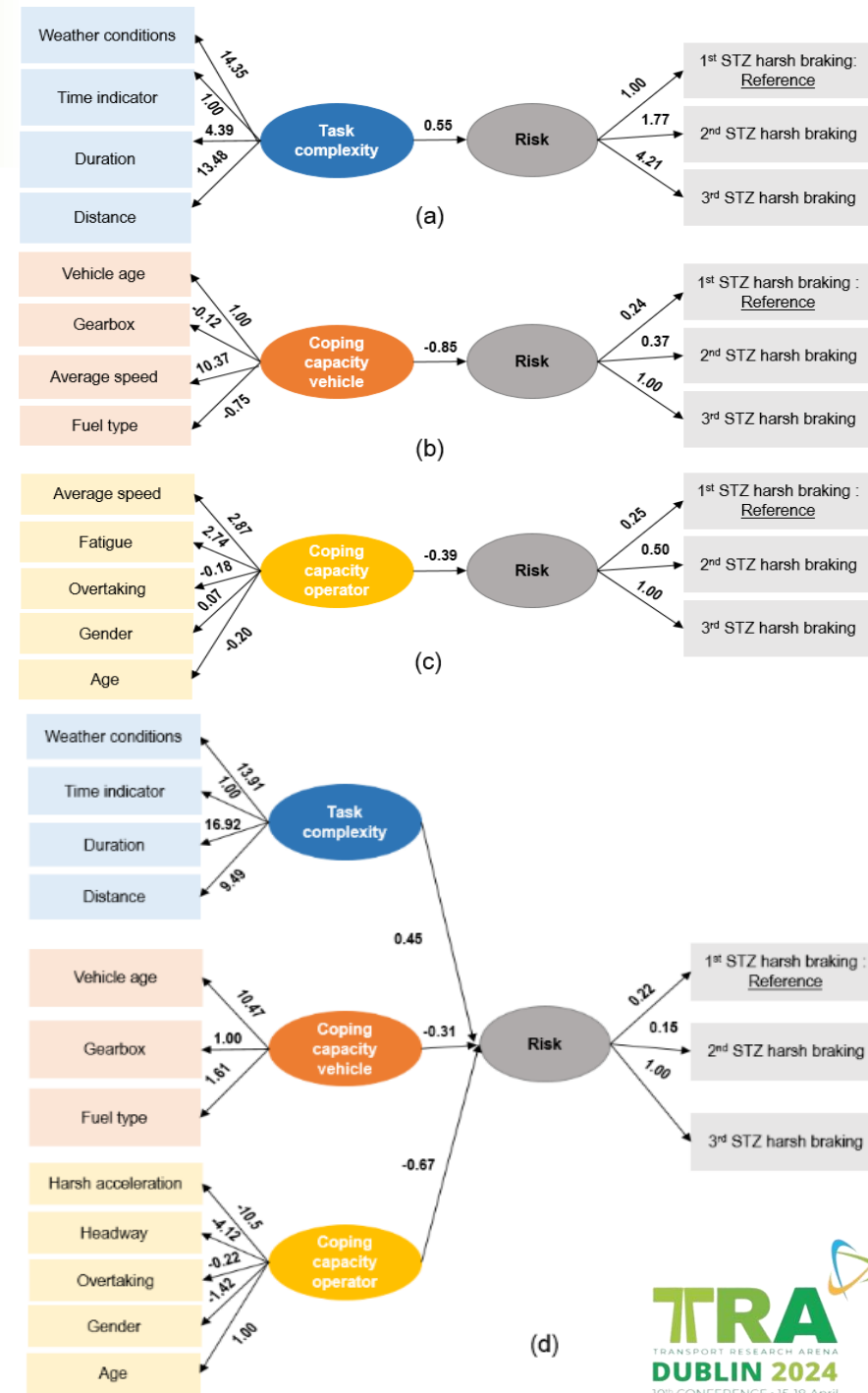
Results - Speeding

- Risk is measured by means of the **STZ (Safety Tolerance Zone)** levels for speeding (level 1 refers to 'normal driving' used as the reference case, level 2 refers to 'dangerous driving' while level 3 refers to 'avoidable accident driving')
- The numbers on the arrows indicate the **correlation** among the variables
- The most important finding is the **positive correlation between the complexity of the driving task and risk**, meaning that increased task complexity relates to increased risk according to the model
- The structural model between **coping capacity and risk shows a negative coefficient**, which means that increased coping capacity relates to decreased risk according to the model



Results - Harsh Braking

- Risk was measured through the types of harsh events and the level of **severity at which they occur**
- For **harsh braking**, there are high severity events (1st STZ level), moderate severity events (2nd STZ level) and low severity events (3rd STZ level).
- Overall, there is a **positive correlation** between task complexity and risk (regression coefficient=0.45), while there is a negative correlation between vehicle and operator state and risk
- On the other hand, SEM between coping capacity and risk shows a **negative coefficient**, which means that increased coping capacity relates to decreased risk (coefficient=-0.31 (vehicle state) / -0.67 (operator state))



Results - Overall

- It was found that **p-values <0.001** across all metrics revealed strong evidence of model fit for both speeding and harsh braking
- For **speeding**, all metrics demonstrated high levels of fit, with CFI values ranging from 0.997 to 0.981, TLI values ranging from 0.994 to 0.969, SRMR values between 0.032 and 0.066, and RMSEA values between 0.052 and 0.101.
- For **harsh braking**, significant p-values alongside CFI values ranging from 0.992 to 0.707, TLI values between 0.987 and 0.613, SRMR values from 0.045 to 0.090, and RMSEA values spanning 0.080 to 0.148 affirm the robustness of the model fit across various dimensions, highlighting its reliability in capturing the complexities associated with both driving behaviors

Model fit metrics	Task complexity	Coping capacity operator state	Coping capacity vehicle state	Synthesis
Speeding				
p-value	<0.001	<0.001	<0.001	<0.001
CFI	0.997	0.992	0.730	0.952
TLI	0.994	0.987	0.601	0.936
SRMR	0.048	0.045	0.153	0.074
RMSEA	0.062	0.080	0.440	0.100
Harsh braking				
p-value	<0.001	<0.001	<0.001	<0.001
CFI	0.981	0.707	0.897	0.832
TLI	0.969	0.613	0.848	0.845
SRMR	0.032	0.090	0.066	0.064
RMSEA	0.052	0.148	0.101	0.085



Discussion

- **Higher task complexity** was associated with an increased crash risk
- Drivers could probably become **overwhelmed** by the demands of complex tasks, leading to reduced attention to the road and other traffic participants
- Increased **coping capacity** relates to decreased **risk** according to the model
- This means that by increasing the coping capacity of both the operators and the vehicles, we can create a **safer driving environment**



Conclusions

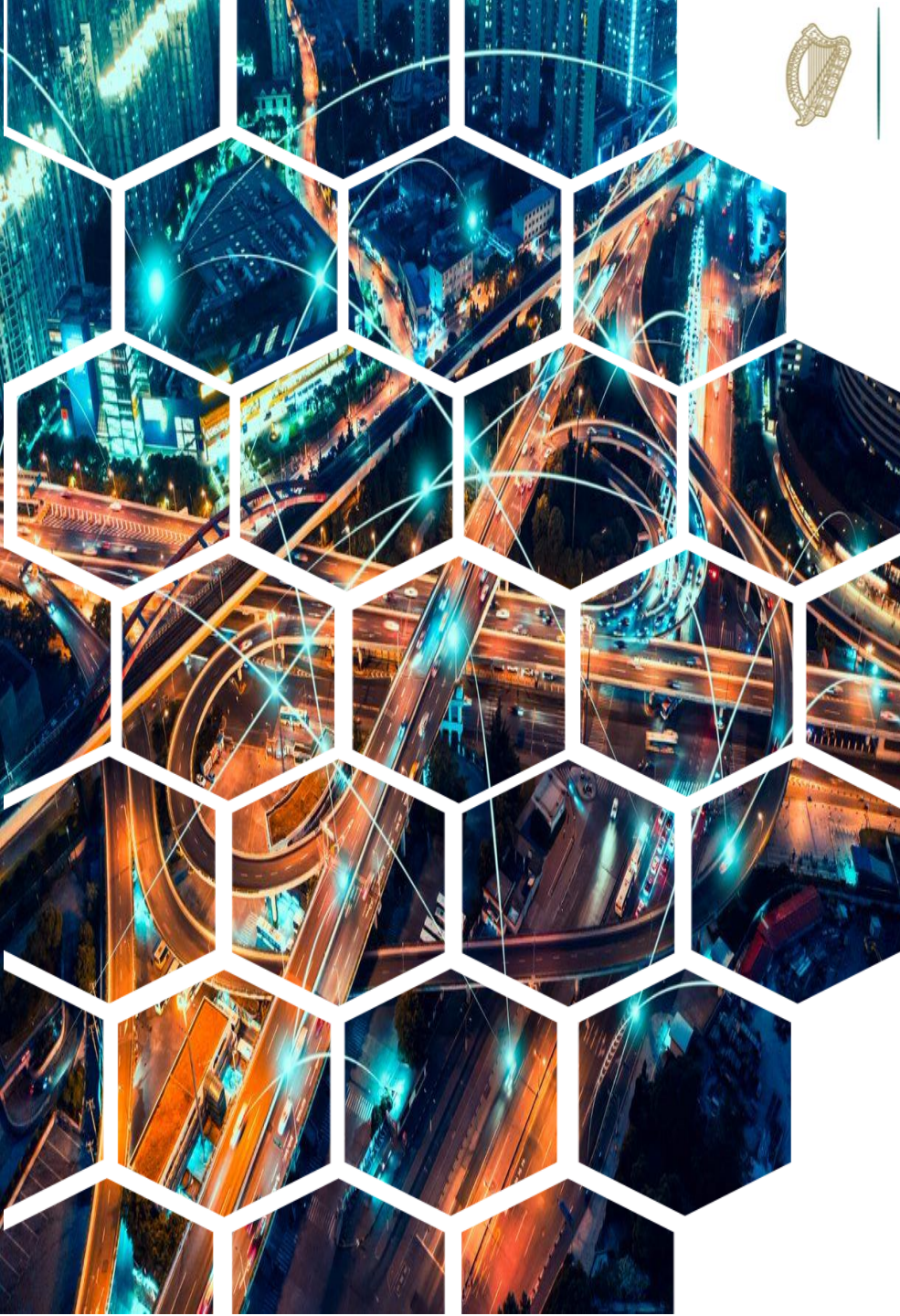
- Results demonstrated that **coping capacity** and **risk** displayed a negative relationship across all phases, indicating that higher coping capacity was associated with reduced risk
- The relationship among **task complexity, coping capacity and risk**, may depend on the specific context and the type of task or activity involved
- Higher **task complexity** may increase the potential for errors or crashes, as it can lead to greater cognitive or physical demands on the individual performing the task
- Similarly, a **higher coping capacity** may help to reduce the risk of crashes or errors, as it can provide individuals with the resources or strategies needed to effectively manage challenging or stressful situations



Future Research

- Future research should take into account other critical factors affecting the **driver's capability** to cope with the **complexity** of driving. For instance, road type and the volume of traffic composition can be critical parameters in defining task complexity
- Develop alternative techniques for examining **feature importance**
- Further investigation of the **significance of variables** can more accurately determine the relationship among variables
- Further improvement of existing or creation of new applications for improving **driving behaviour** to obtain more accurate data and variables to be exploited





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