

A Review on Legal Consideration and Liability Allocation Connected and Automated Vehicles

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ICTR 2025

12th International Congress on Transportation Research

16-18 October 2025, Thessaloniki, Greece



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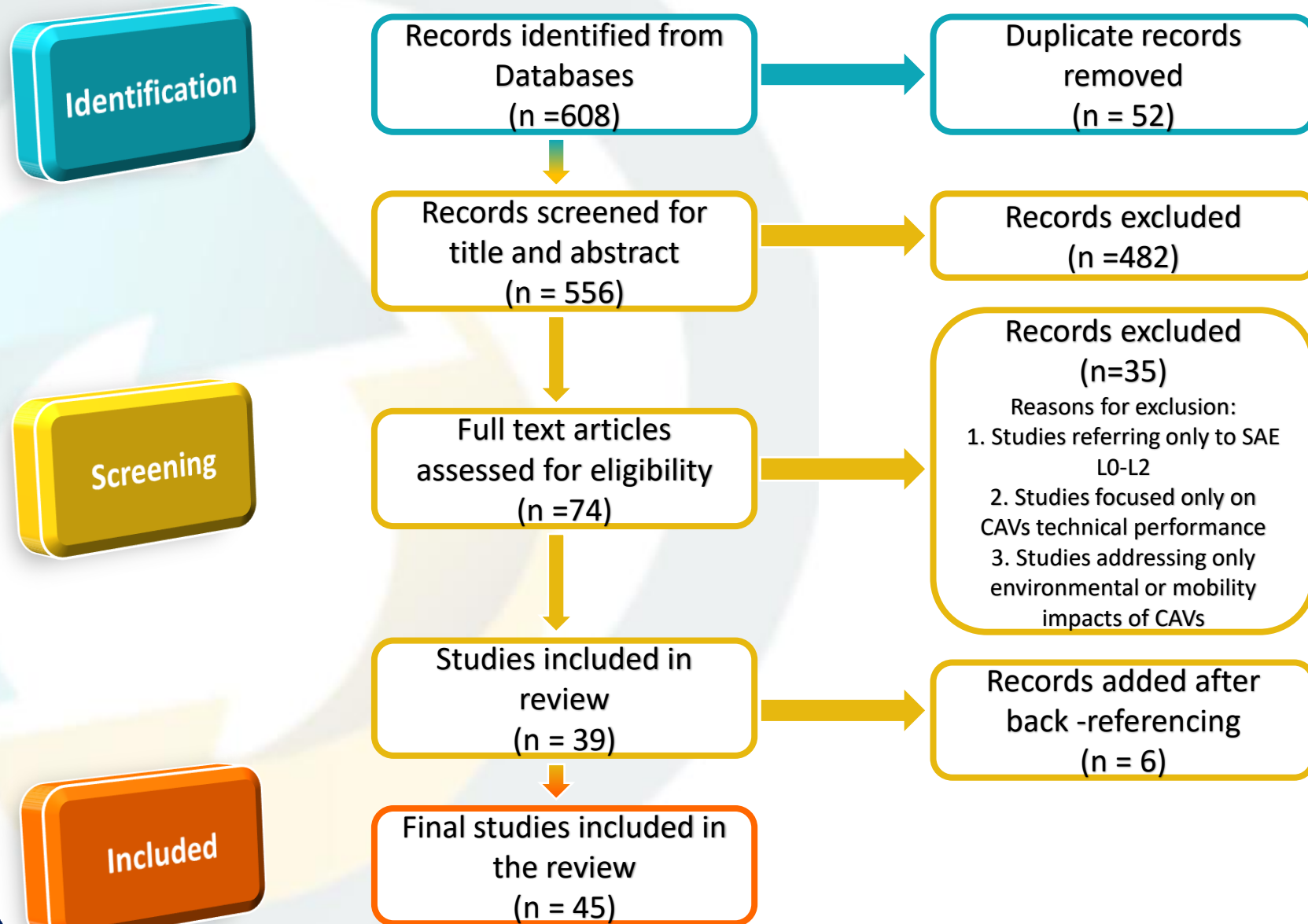
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Introduction

- Connected and Automated Vehicles (CAVs) are **reshaping transport** by promising safer roads, reduced congestion, lower emissions, and improved mobility for vulnerable groups.
- Levels 3–5 automation can take over most or all driving tasks, aiming to **eliminate human error** as a primary cause of crashes.
- However, during the **transition phase** when human-driven and automated vehicles share roads, interactions with pedestrians, other VRUs and conventional vehicles will become complex.
- **Legal uncertainty** and poorly developed liability frameworks are major barriers to the safe and efficient deployment of CAVs.



Literature Review Methodology



Legal Frameworks across Jurisdictions

- **Legal readiness for CAVs varies** greatly between countries, both in terms of technical adoption and legal liability provisions.
- **Europe** (Germany, France) has developed **advanced laws assigning responsibility to manufacturers**, requiring safety approvals and data recording.
- **China pursues rapid AV deployment** but has inconsistent local regulations, while the **U.S. relies on fragmented state laws** with little federal guidance.
- The Vienna Convention (2016) allows automated systems if human override is possible, but most countries still rely on soft, non-binding guidelines, leaving **cross-border liability unclear**.



Liability Allocation Models

- **Traditional liability frameworks** assume a human driver is always at fault, which is **incompatible with** shared or fully **automated driving**.
- Studies show that even when systems are in control, public opinion often still blames the human occupant ("**moral crumple zone**").
- Proposed solutions include **shifting the burden of proof to manufacturers**, using comparative negligence to share fault, or creating enterprise liability where one entity takes full responsibility.
- **Clear legal definitions** of "driver" and "control" are urgently needed, alongside international harmonization to prevent legal uncertainty from slowing adoption.



HMI and Legal Ambiguity

- SAE Level 3–4 systems require **drivers to retake control in emergencies**, but studies show they often respond slowly after long periods of disengagement.
- **Current laws** do not clarify whether liability lies with the driver for failing to react or with the system for issuing an unsafe handover.
- **Poor interface design** and weak warning systems worsen this issue, suggesting liability could shift to manufacturers or software developers.
- **Legal solutions** proposed include event data recorders (EDRs), biometric driver logging, and formal traffic rule logic to **document who had control and when**.



Ethical and Social Considerations

- AVs introduce **new ethical questions**, such as how they should behave in unavoidable crash scenarios — often discussed via the “trolley problem.”
- **Public attitudes are inconsistent**: people say they want AVs to act for the greater good, but also want their own vehicles to prioritize their safety.
- **Ethical preferences vary across cultures** (e.g. Japan collectivists vs US individualists), making global ethical rules difficult to enforce, while manufacturers often focus more on minimizing risk and liability than on abstract ethics.
- **Social equity issues** also arise: CAVs could expand access for elderly and disabled users but may worsen inequality and public health if they reduce walking, cycling, and public transit use.



Insurance and Economic Impacts

- **Traditional car insurance** relies on assigning fault to an individual driver, which does not fit CAVs that involve multiple actors like OEMs, software firms, and infrastructure managers.
- The insurance industry is experimenting with new approaches: **shared liability**, **product liability** that shifts responsibility to manufacturers, and real-time data sharing.
- Risk models are being redesigned to **incorporate telematics and contextual data** rather than just human driving records.
- While widespread CAV use could save costs from fewer crashes and optimized travel, **legal uncertainty currently delays insurance innovation** and raises premiums.



Discussion (1/2)

- **Regulatory frameworks are fragmented across jurisdictions**, leaving manufacturers and users to navigate conflicting standards and unclear safety requirements.
- Legal systems still rely on **human-fault logic**, which does not align with automation where control is shared or entirely delegated to machines.
- **Lack of standardized EDRs** and data access protocols undermines fair investigations and insurance claims.
- **Ethical rules are underdeveloped** and culturally inconsistent, while the insurance industry struggles to adapt to complex multi-party liability networks.



Discussion (2/2)

- **International harmonization of legal definitions**, safety requirements, and liability rules is essential to enable cross-border CAV deployment.
- Flexible, **evidence-based liability systems** should replace rigid driver-fault models, distributing responsibility among all actors involved.
- Standardized tamper-proof EDRs and clear data access rights can **provide reliable evidence for insurers and courts**.
- **Public trust must be strengthened** through education, demonstrations, ethical transparency, and engagement of ethicists, engineers, and policymakers in decision-making.



Conclusions

- CAVs offer transformative **safety and mobility benefits**, but legal, ethical, and insurance systems remain unprepared for their widespread use.
- **Liability frameworks** are still fragmented and human-centered, hindering innovation and public acceptance.
- Research is needed to test **how liability models affect safety**, user behavior, and manufacturer incentives in real traffic.
- Clear, **harmonized legal rules** are critical for building trust, ensuring safety, and realizing the promised benefits of automated mobility.
- Updated regulatory frameworks should consider manufacturers' **holistic safety** initiatives (e.g. Waymo)



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