



Driver Foot Behavior with Regenerative Braking

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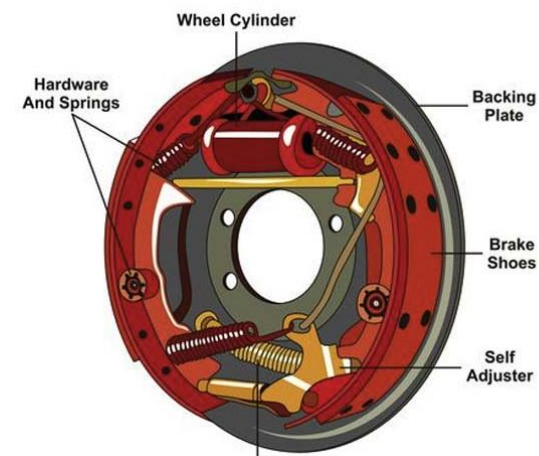
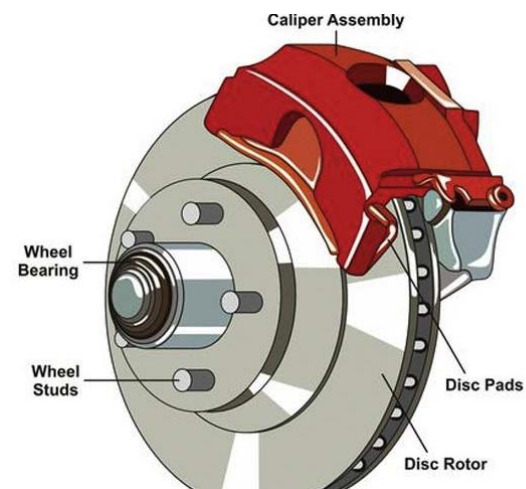
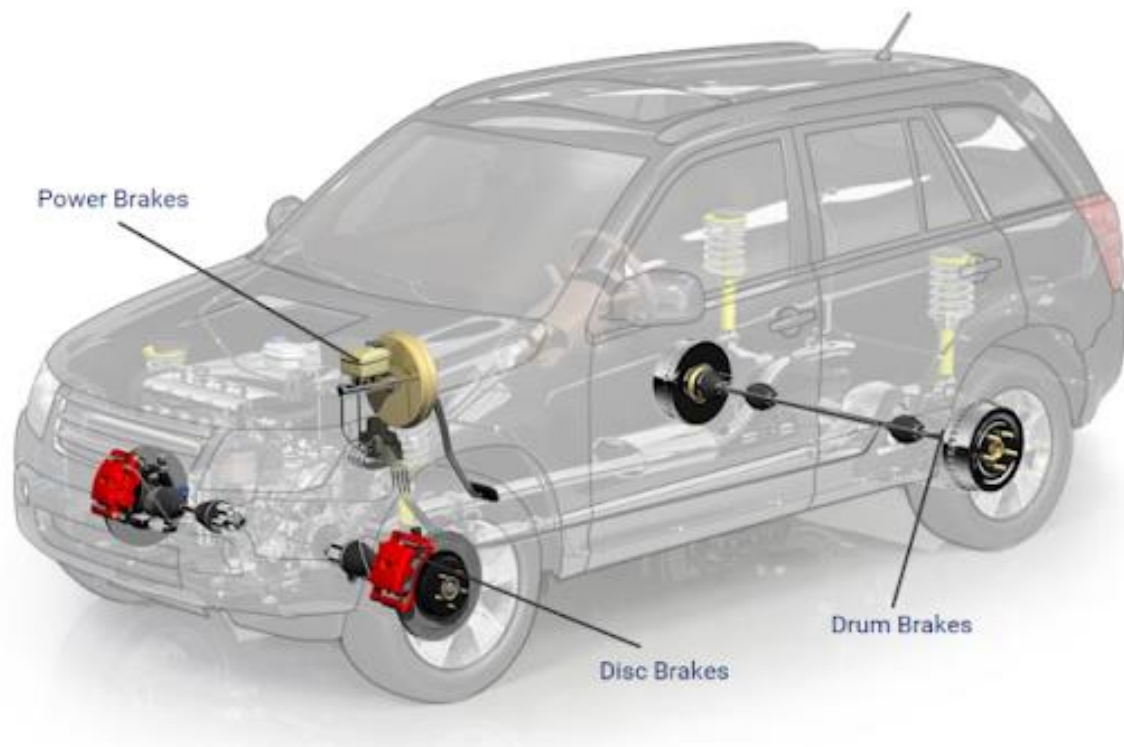
Daniel V. McGehee, Ph.D.

Chris Schwarz, Ph.D.

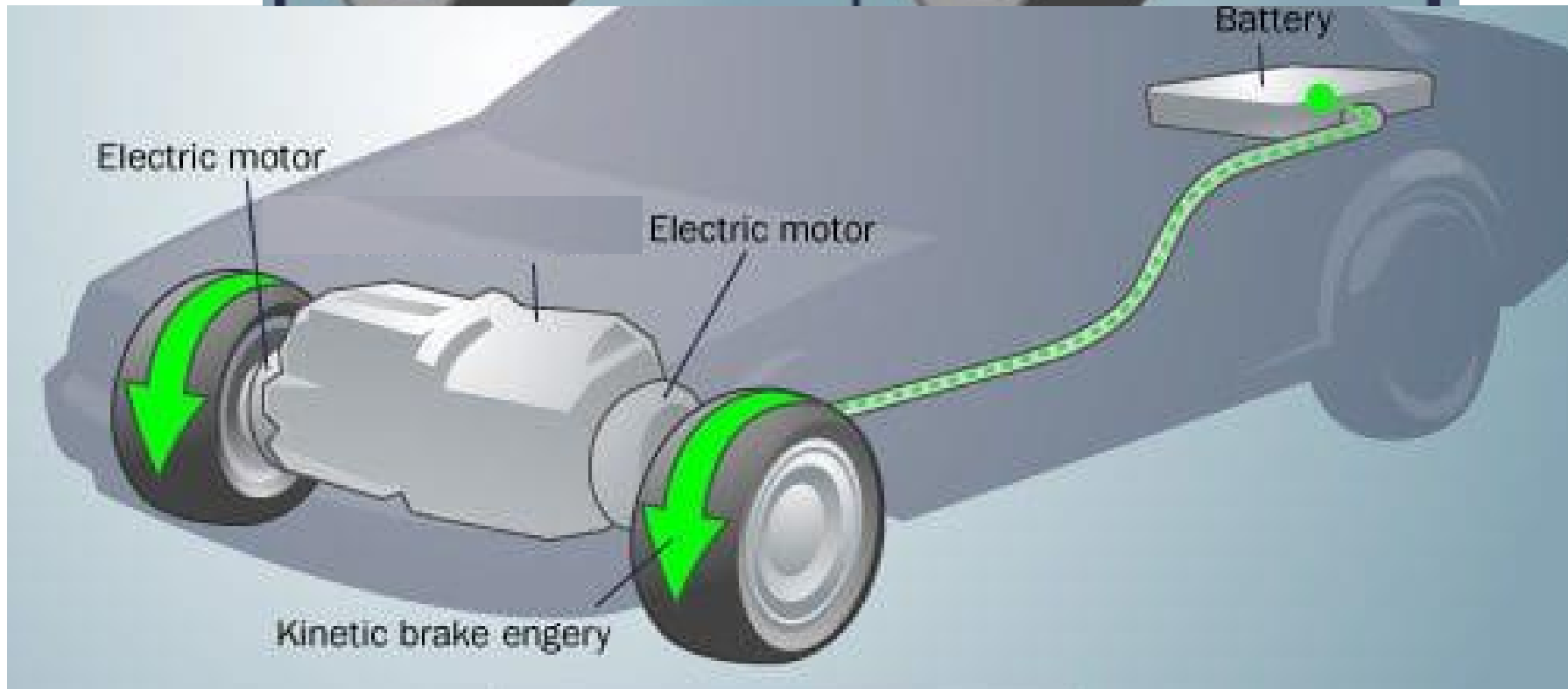
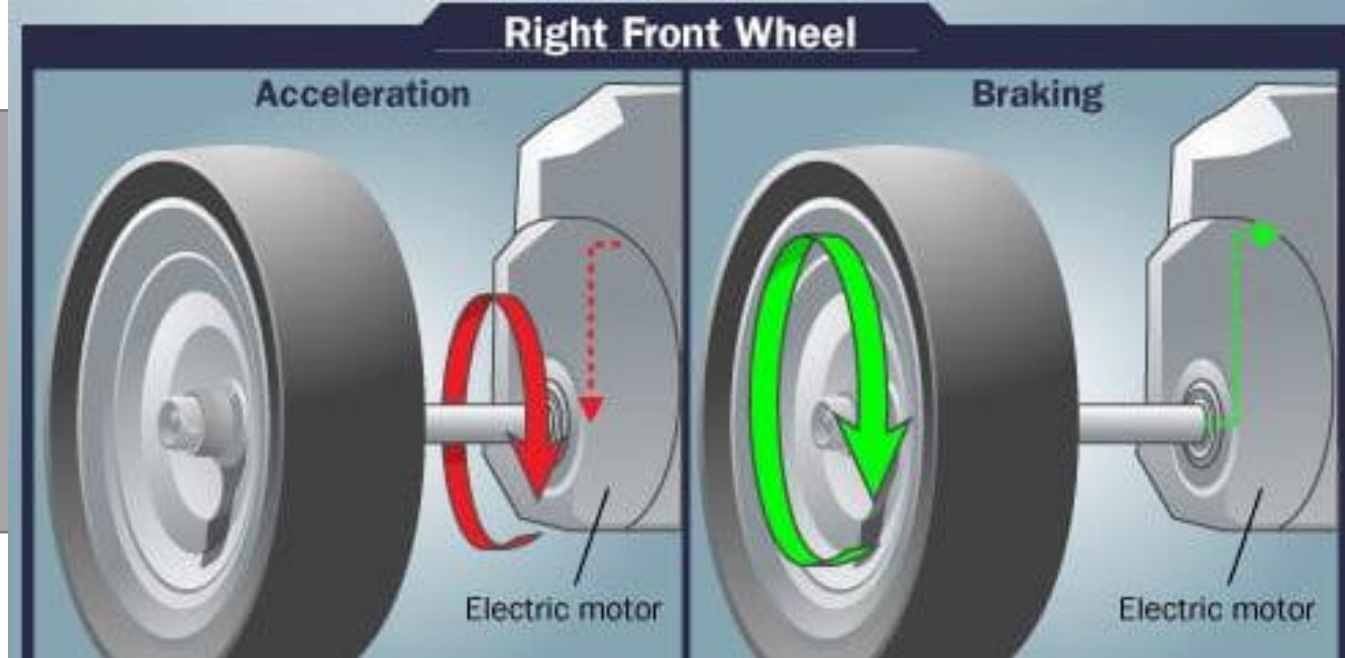
The University of Iowa

National Advanced Driving Simulator

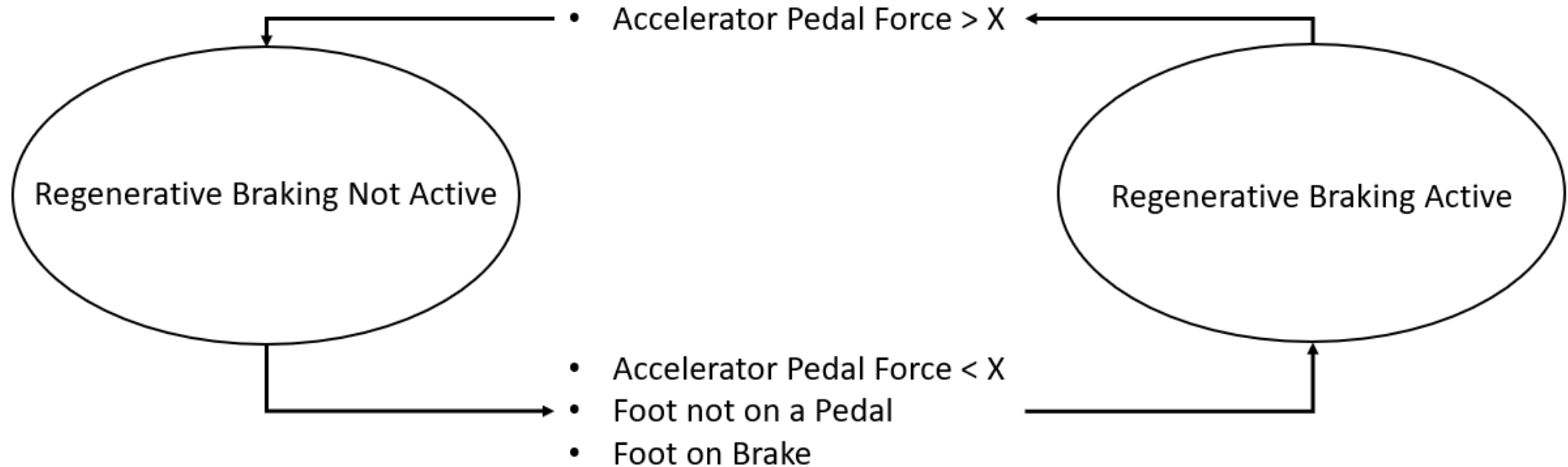
Service Braking (SB)



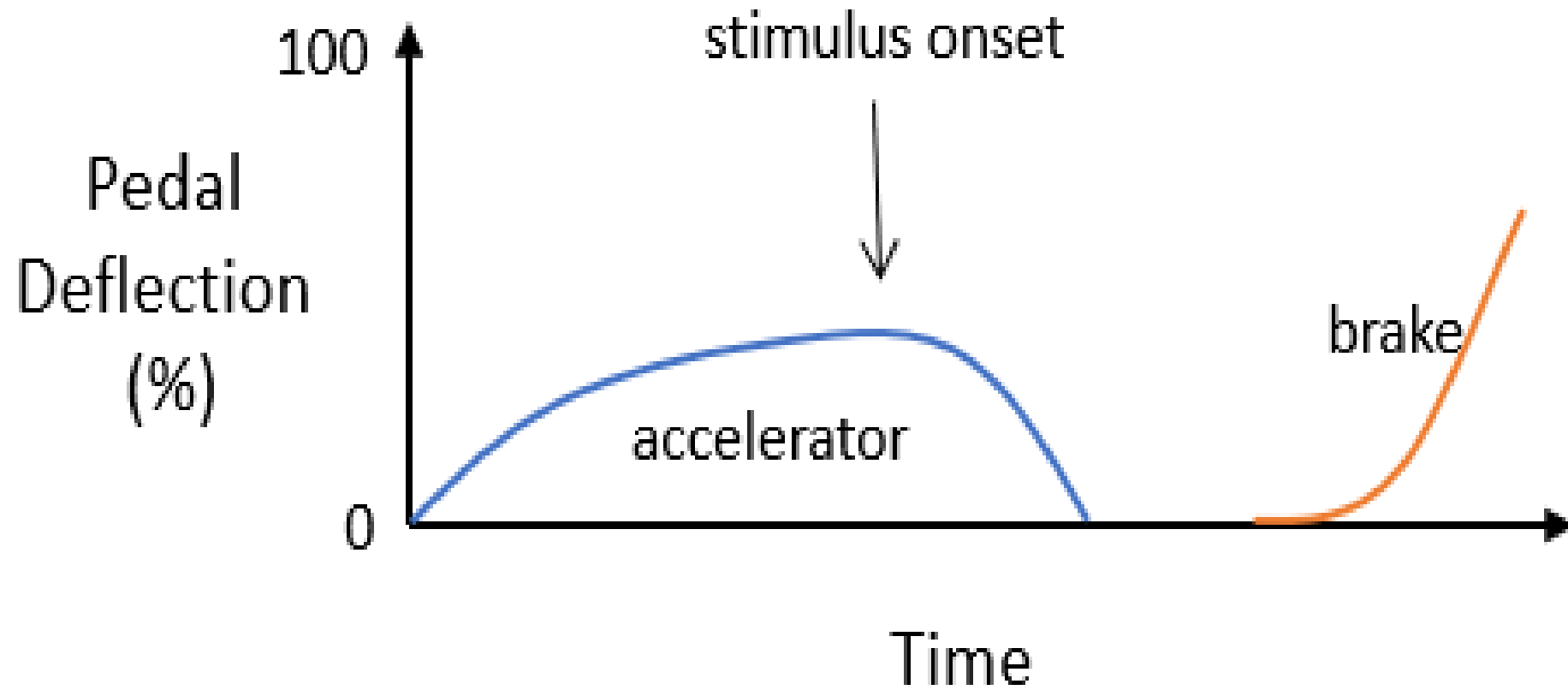
Regenerative Braking (RB)



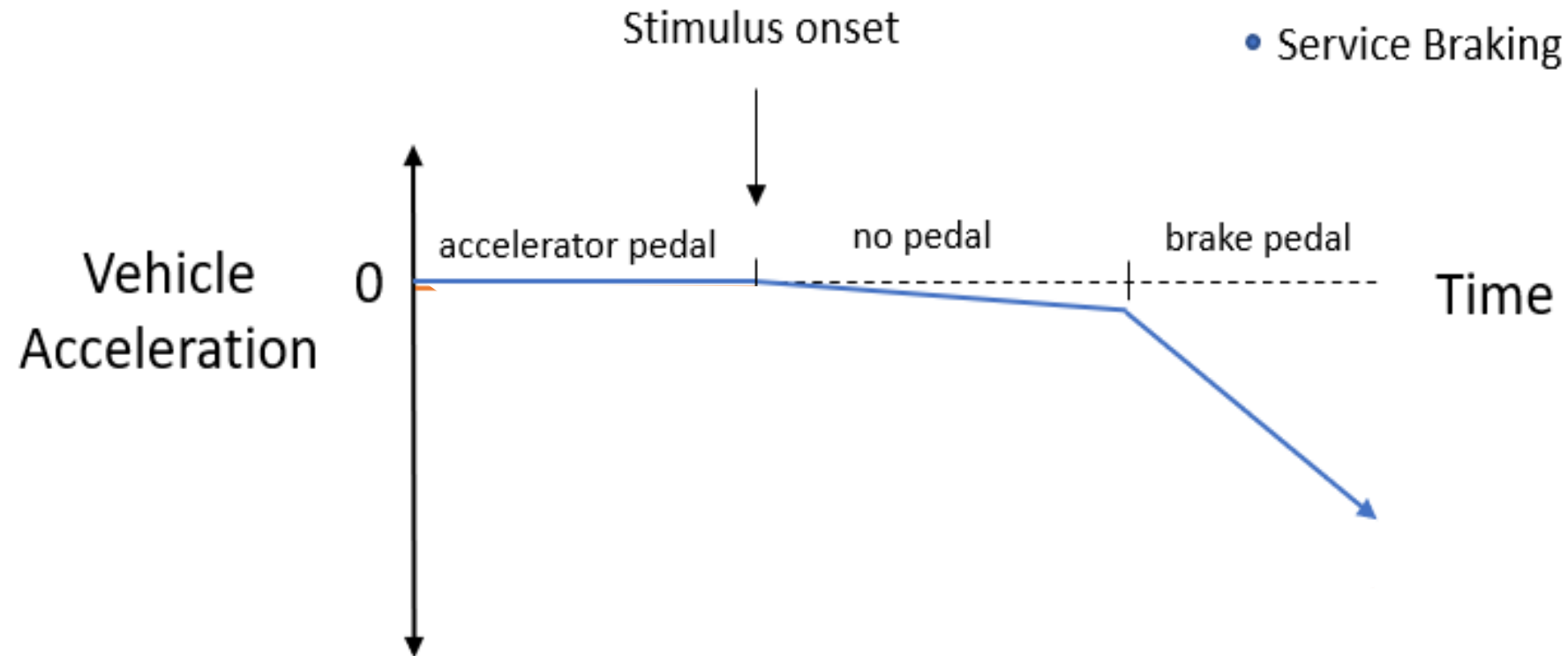
Regenerative Braking (RB)



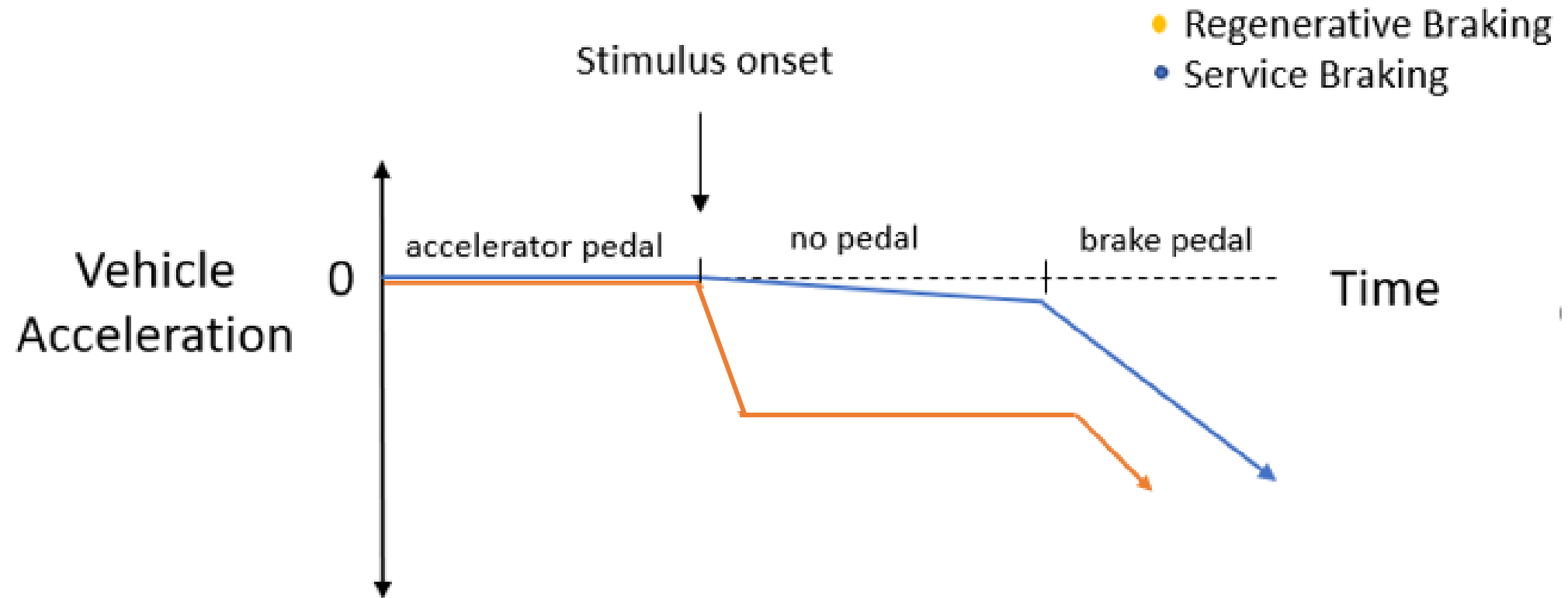
Driver Braking Behavior



Driver Braking Behavior with Traditional Service Braking



Driver Braking Behavior with Regenerative Braking



Literature Gaps

- Little research regarding human factors and RB
 - Cocron et al. (2013) explored how quickly drivers learn RB systems
 - Other research looks at RB from an implementation standpoint
- Differences in driver behavior between RB and SB has not been explored



Research Question

1. Is there a difference in driver foot behavior between RB and SB?

Study Design

3 Braking Conditions

- Service Braking (deceleration of 0.01-0.04 g)
- Low level of RB (deceleration of 0.02-0.05 g)
- High level of RB (deceleration of 0.15-0.2 g)


30 participants (randomly assigned to condition)

- 10 per condition (5 female, 5 male)

Between subjects design



Equipment



The Simulated Drive

- Driver was instructed to drive 55 mph.
- Lead vehicle in front of participant vehicle throughout the drive (fixed gap).
- 3 separate braking events.
- Rural two-lane highway.
- Day-time, light traffic.

Data

- Simulator data
- Video data was also used for coding purposes





Time Based Measures

- Time period from accelerator release to brake press
- Time period from lead vehicle brake lights illuminating to accelerator release



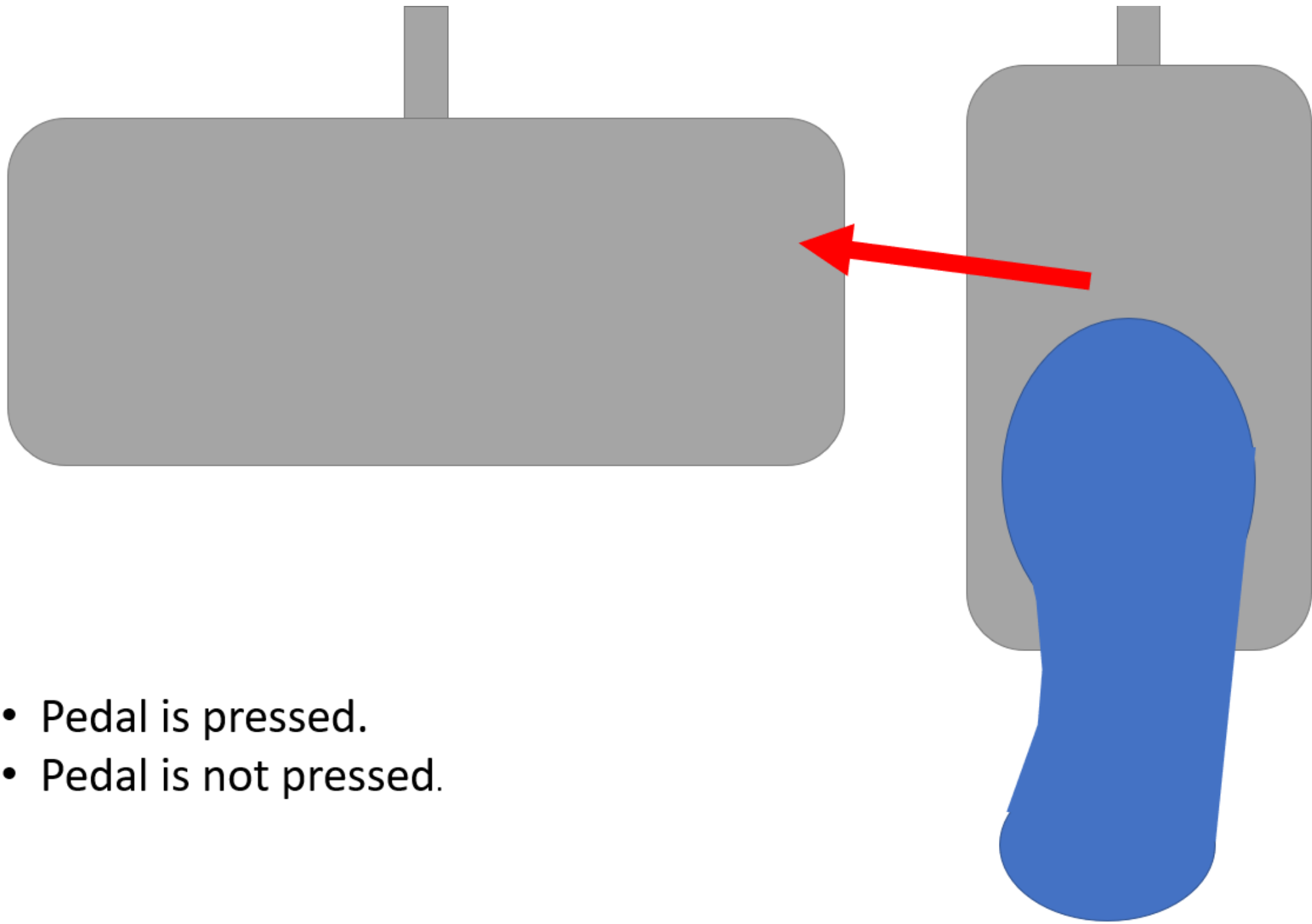
Driver Foot Behavior Categories (adapted from McGehee et al, 2016)

Category Number	Description
1	Wrong pedal press
2	Pedal miss
3	Both pedals pressed
4	Pedal slip
5	Uncertainty – “wagging foot”
6	Back pedal hook
7	Near-miss, reposition of foot
8	Brake tap, reposition to throttle, brake press (new)

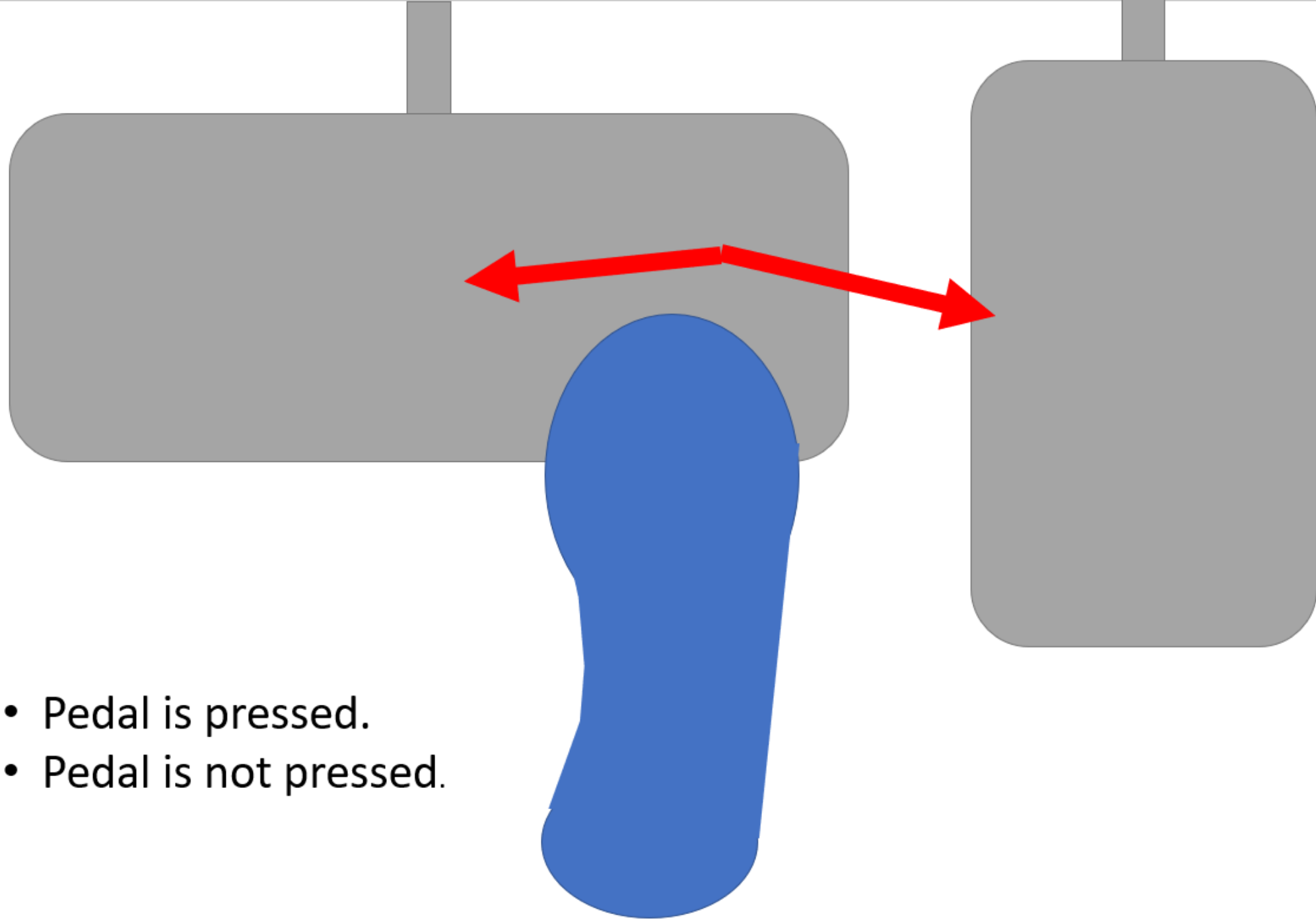
START

- Pedal is pressed.
- Pedal is not pressed.

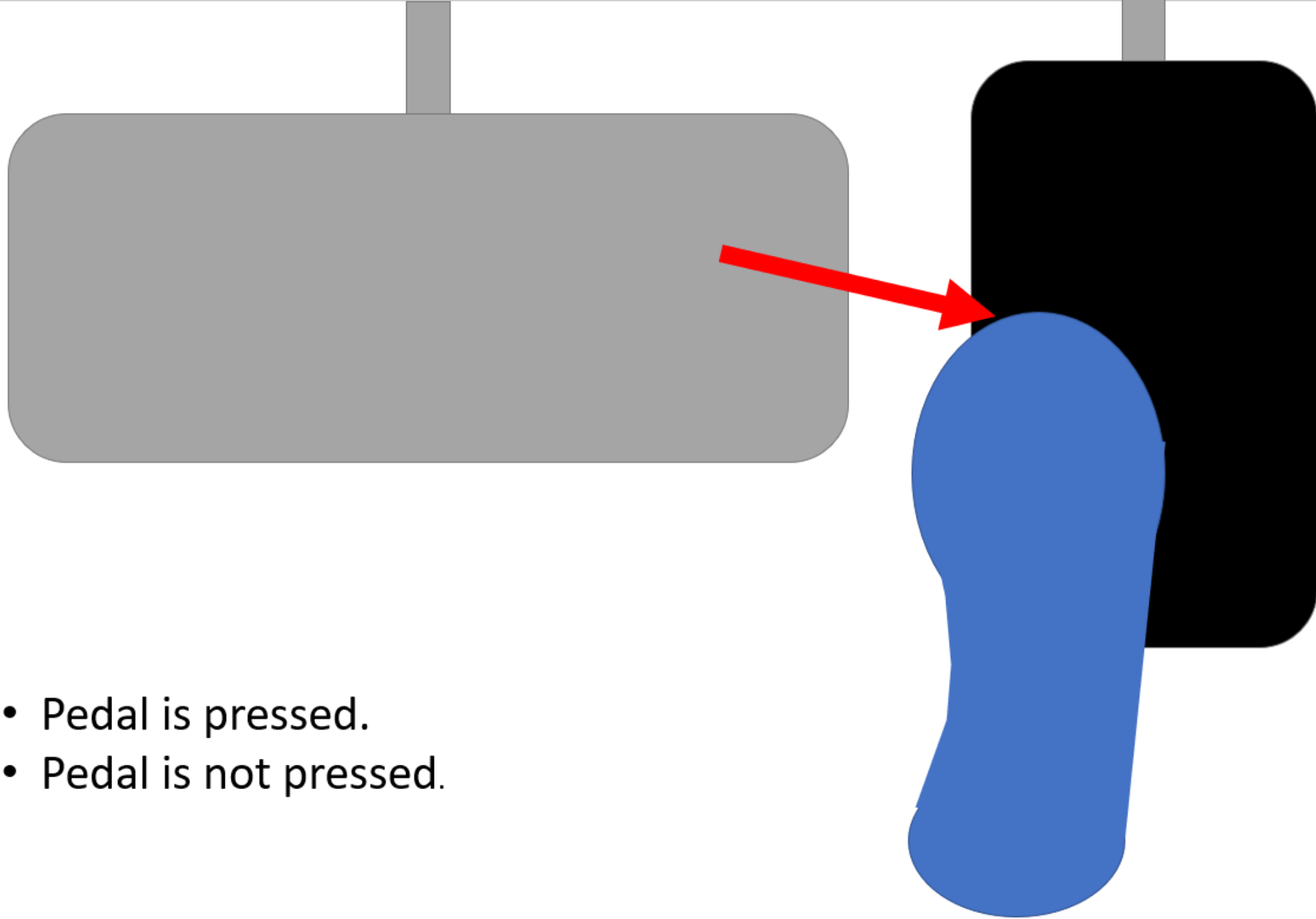




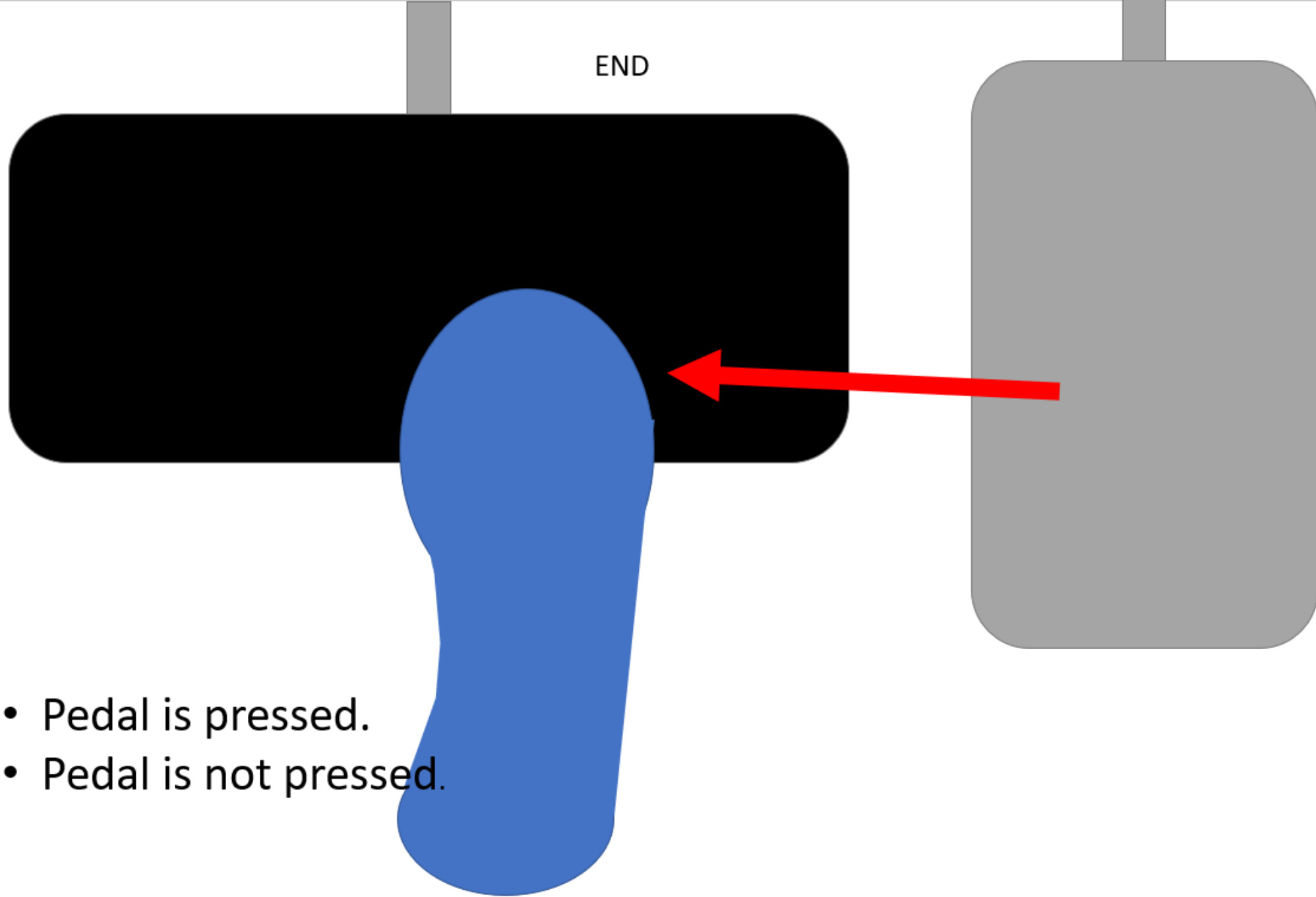
- • Pedal is pressed.
- • Pedal is not pressed.



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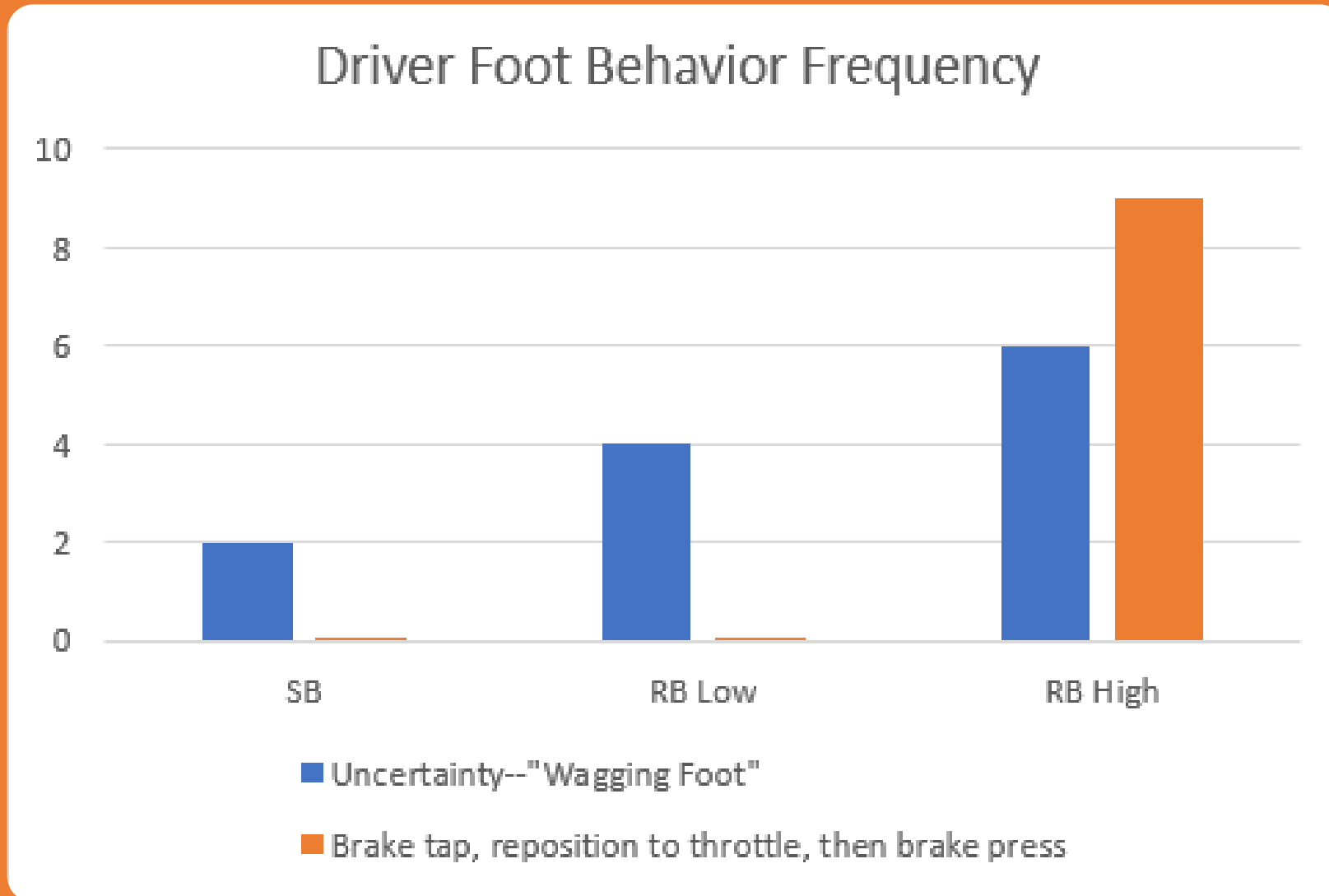
- • Pedal is pressed.
- • Pedal is not pressed.



Video Coding Results

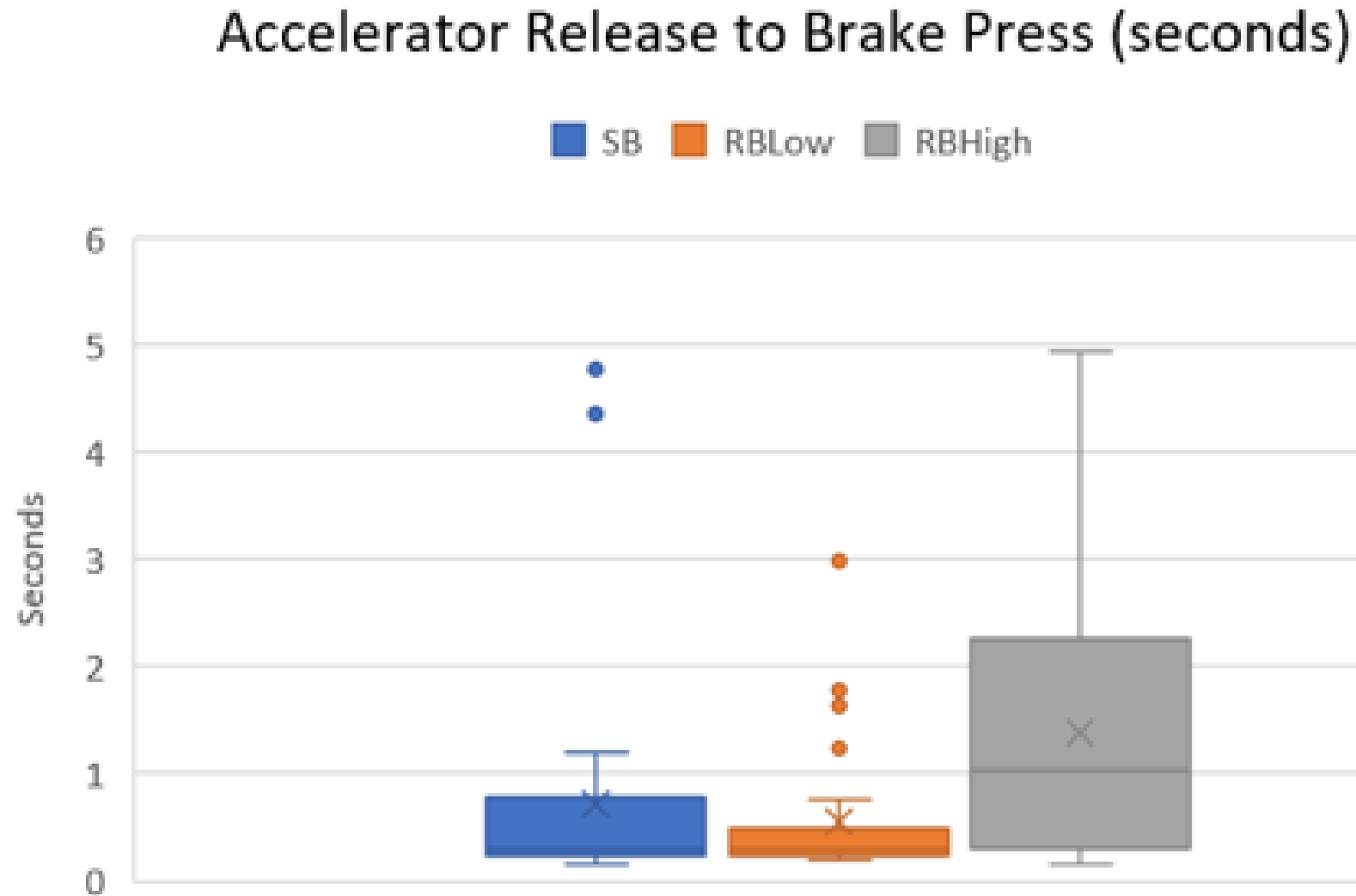
	SB	RBLow	RBHigh	Kruskal Wallis H
n	30	30	27	
Uncertainty— “wagging foot” (5)	2 (7%)	4 (13%)	6 (22%)	p=0.5997
Near-miss, reposition of foot (7)	0 (0%)	1 (3%)	0 (0%)	p=0.96813
Brake tap, reposition to throttle, then brake press (8)	0 (0%)	0 (0%)	9 (33%)	p=0.04651

Video Coding Results

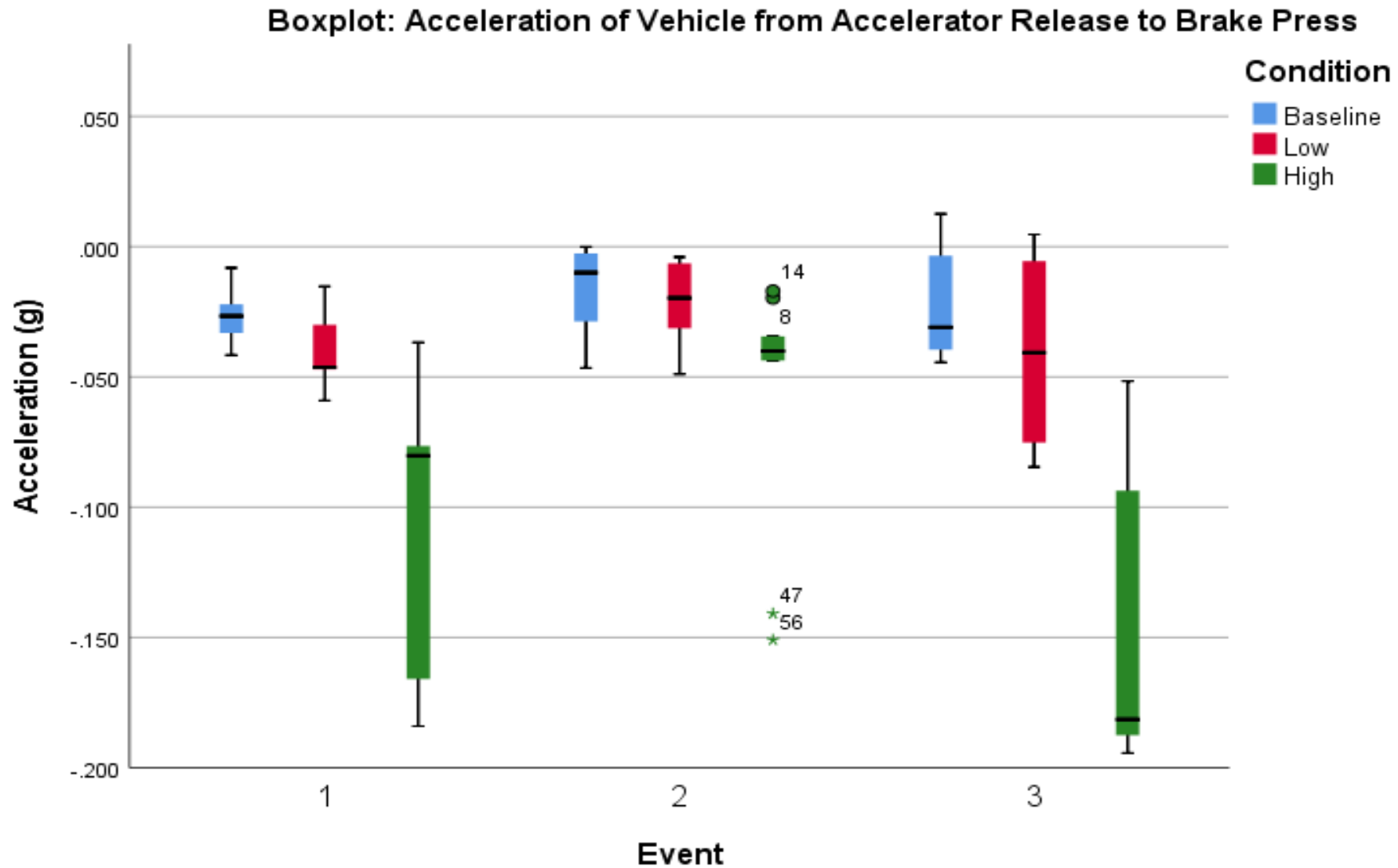


Conditions	SB, RBLow	SB, RBHigh	RBLow, RBHigh	SB, RBLow, RBHigh
Kruskal-Wallis H/Mann-Whitney U	0.001	6.185	6.468	8.339
Degrees of Freedom	1	1	1	2
Asymptotic Significance	0.976	0.03	0.011	0.015

Time Based Measures Results

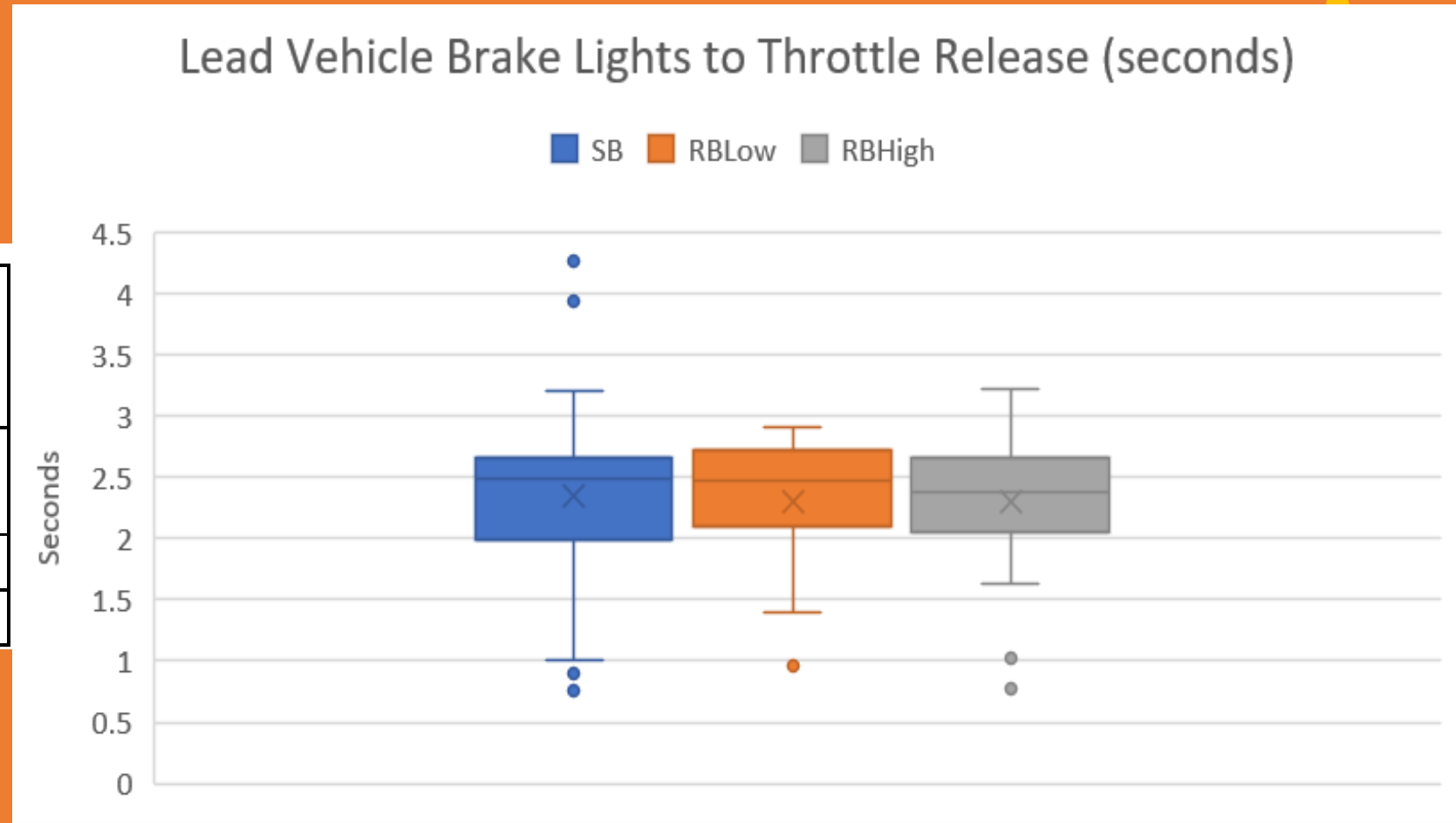


Time Based Measures Results



Time Based Measures Results

Conditions	SB, RBLow, RBHigh
Kruskal-Wallis H/Mann-Whitney U	0.367
Degrees of freedom	2
Asymptotic significance	0.832



Discussion

