

9^ο ΔΙΕΘΝΕΣ ΣΥΝΕΔΡΙΟ για την
ΕΡΕΥΝΑ ΣΤΙΣ ΜΕΤΑΦΟΡΕΣ
ΜΕΤΑΦΟΡΕΣ 4.ο: Η Ευφυής Εξέλιξη



9th INTERNATIONAL CONGRESS on
TRANSPORTATION RESEARCH
TRANSPORT 4.o: The Smart Evolution

What is your driving identity? Some empirical findings using large-scale smartphone sensors' data

Eleni Mantouka, PhD Candidate



NTUA - School of Civil Engineering
Department of Transportation Planning and Engineering



Understanding driving behavior

- Helps to identify the circumstances under which abnormal and unsafe driving events take place
- Is useful for the development of advanced driving assistance and recommendation systems



Real-time recommendations for safer and more efficient driving

- Remains vital even in the era of autonomous and connected vehicles.



Development of acceptable and user friendly “machines”

Benefits of improved driving behavior



Road safety & Traffic

Less car accidents
Improved traffic conditions



Environment

Air pollution



Public health

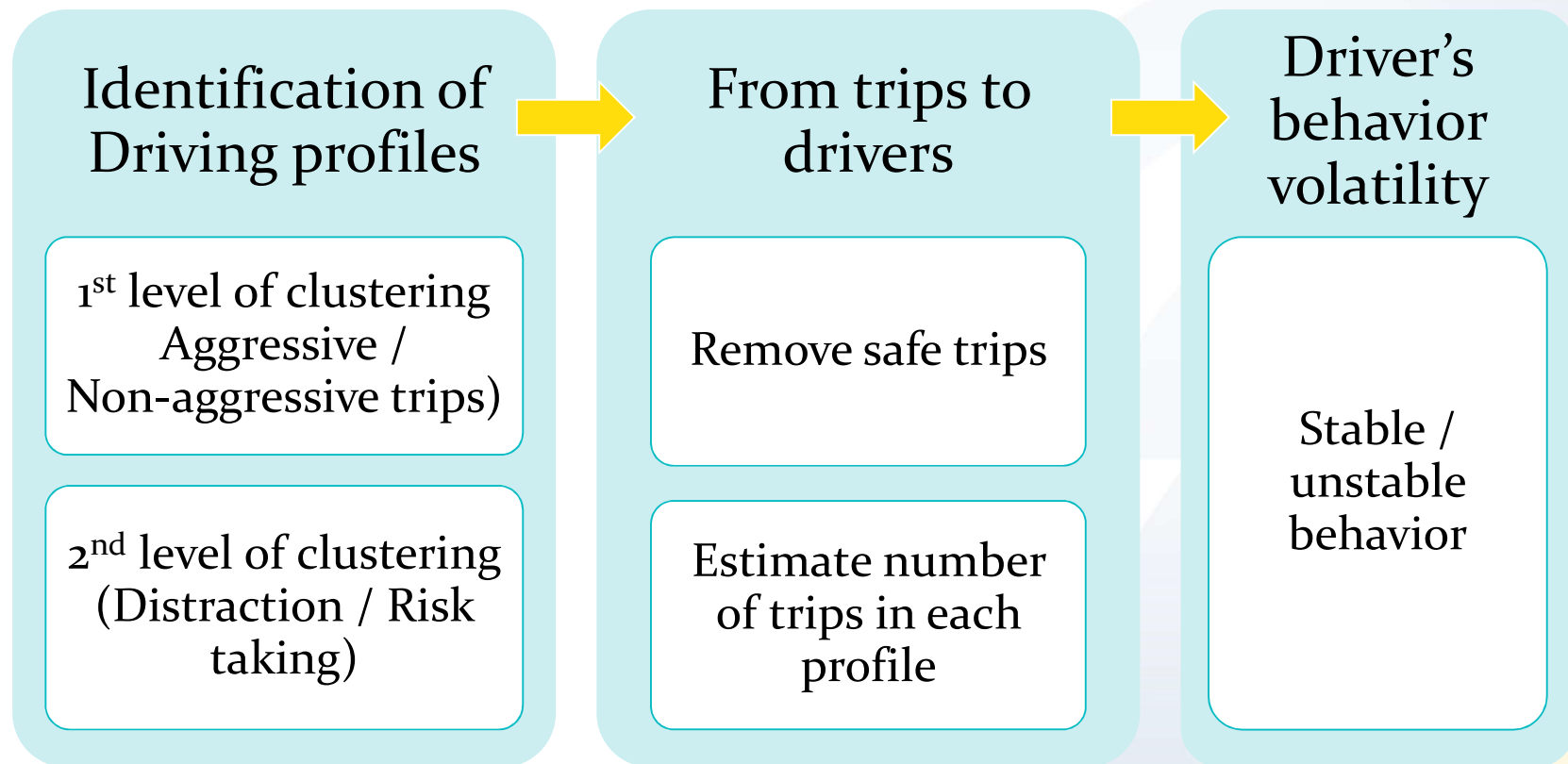
Emissions
Noise

What do we aim to do?

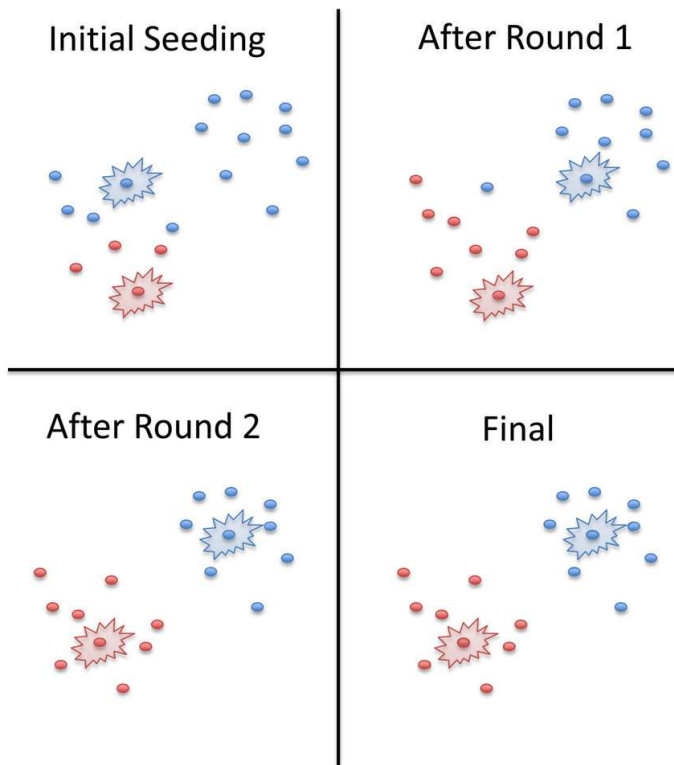
- Identify different driving behaviors
- Distinguish safe from unsafe driving styles
- Rank driving behaviors with regards to road safety
- Investigate each driver's behavior volatility in terms of unsafe driving habits



Methodological approach

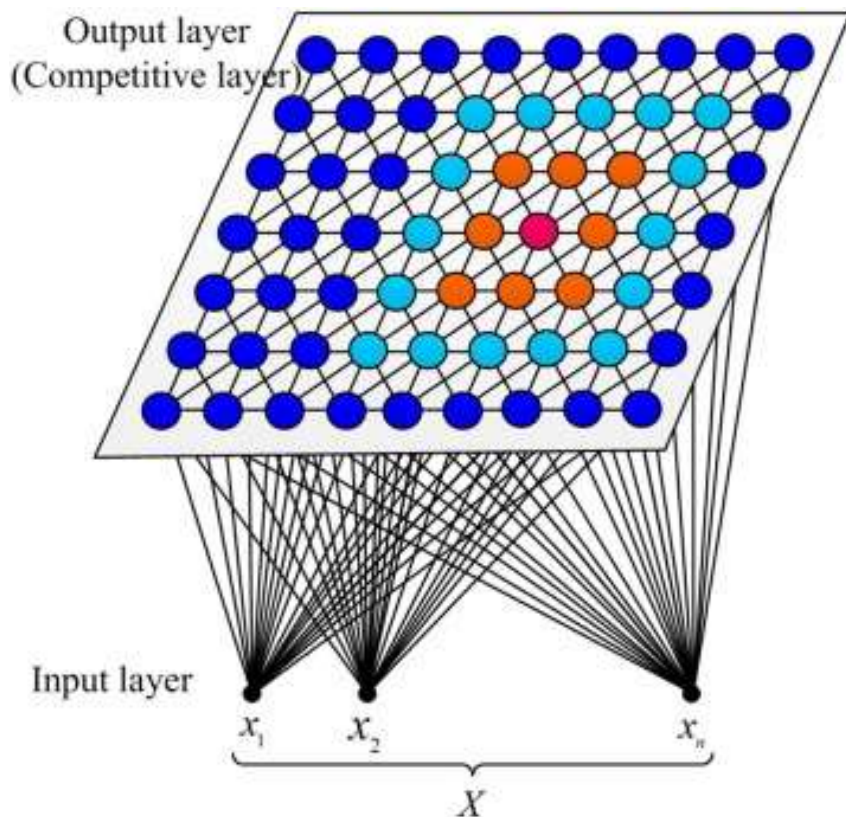


Methodology: K-means Clustering



- Aims to partition n observations into k clusters
- Each observation is assigned to the cluster with the nearest mean
- Number of clusters is chosen using the Elbow method

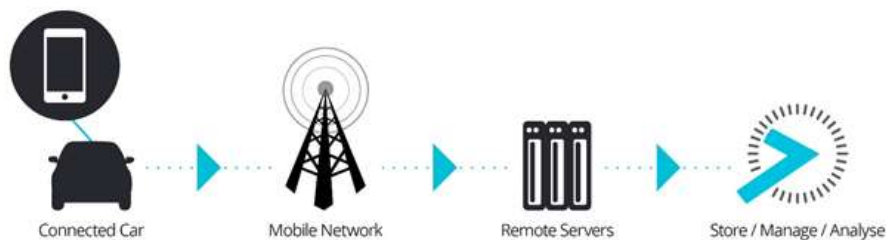
Methodology: Self-Organizing Maps



- A type of Artificial Neural Network (ANN)
- Is trained using unsupervised learning
- Two-dimensional, discretized representation, called a **map**

Smartphone data

Data used are collected through the Oseven app (www.oseven.io)



More than **240000 trips** were available, performed by more than **200 drivers** in Attika Region.

Variables

Harsh acceleration events

Percent of trip duration over the speed limit

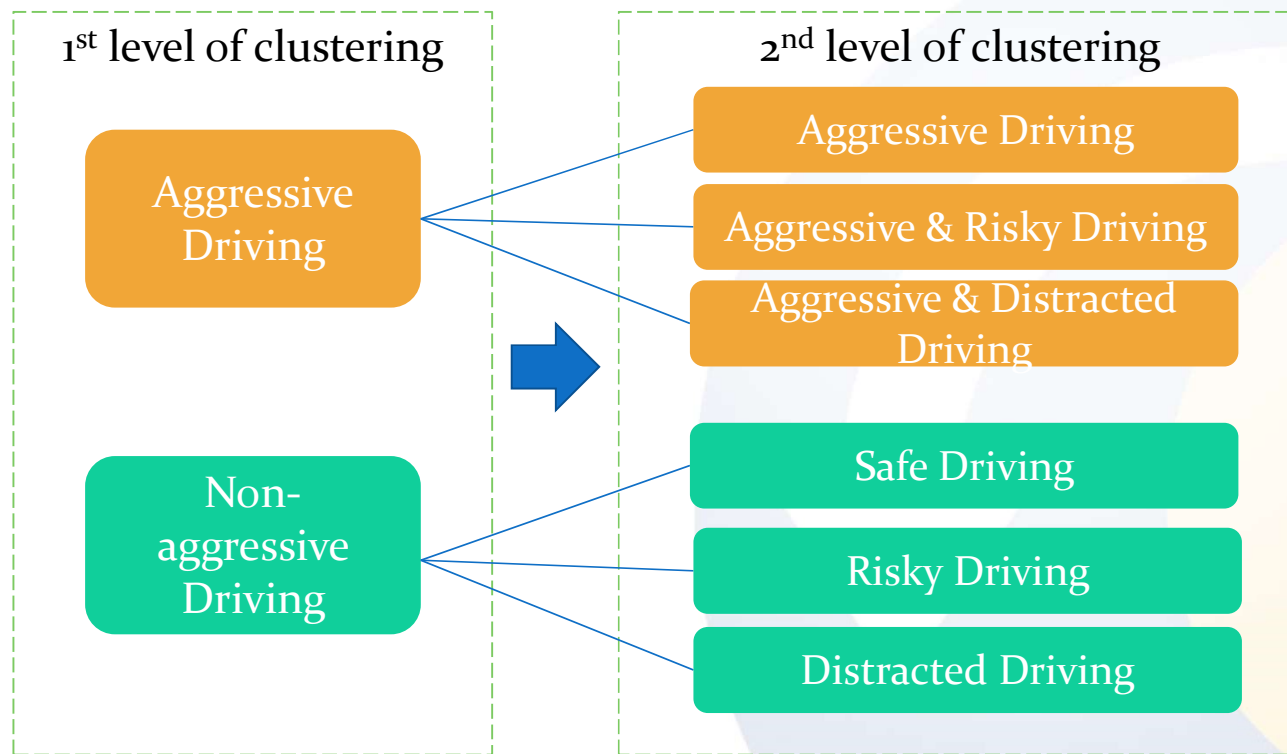
Harsh braking events

Percent of mobile usage

Acceleration

Smoothness indicator

Clustering Results: Driving profiles



Clustering Results: 1st level of clustering

Cluster centers for Aggressive and Non-aggressive trips

| Variable / Cluster | Harsh Acceleration/km | Harsh Brake/km | Smoothness Indicator | Standard Deviation of Acceleration | Number of trips |
|----------------------|-----------------------|----------------|----------------------|------------------------------------|-----------------|
| Aggressive trips | 0.281 | 1.801 | 0.455 | 0.509 | 25731 |
| Non-aggressive trips | 0.038 | 1.169 | 0.299 | 0.093 | 63212 |

- 71% of trips are not featured by aggressiveness
- In case of aggressive trips the number of harsh acceleration events are almost 7 times more than in the case of non-aggressive, while the same number for the harsh brake events is less than 2.

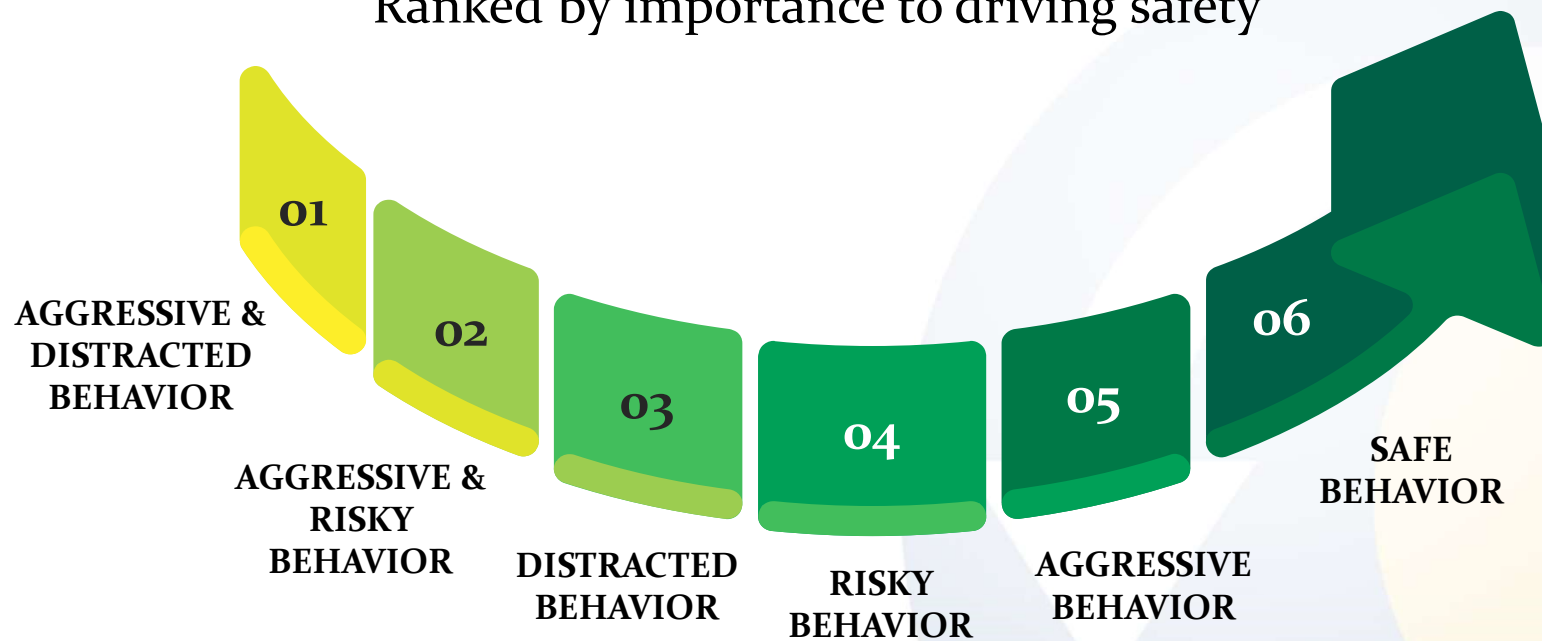
Clustering Results: 2nd level of clustering

| Variable / Driving profile | Percentage of mobile usage | Percent of speeding |
|-----------------------------|----------------------------|---------------------|
| NON-AGGRESSIVE TRIPS | | |
| Distracted | 0.540 | 0.065 |
| Risky | 0.029 | 0.289 |
| Safe | 0.013 | 0.024 |
| AGGRESSIVE TRIPS | | |
| Risky | 0.038 | 0.292 |
| Aggressive | 0.20 | 0.032 |
| Distracted | 0.547 | 0.100 |

- The percent of speeding in case of non-aggressive distracted trips is almost 2 times greater than the corresponding percentage for aggressive distracted trips.
- In both aggressive and non-aggressive trips distracted trips constitute less than 8% of the sample

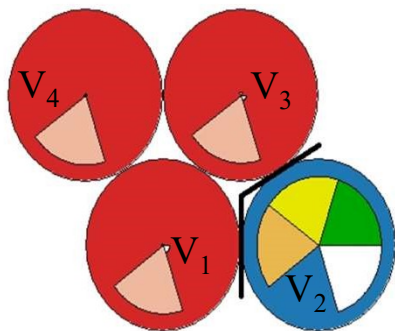
Ranking of driving behavior

Ranked by importance to driving safety



SOM for unsafe driving

| SOM component | Driving profiles | | | | |
|----------------|------------------|-------|------------------|------------|-----------------------|
| | Distracted | Risky | Aggressive-Risky | Aggressive | Aggressive-Distracted |
| V ₁ | 0.044 | 0.107 | 0.059 | 0.759 | 0.030 |
| V ₂ | 0.168 | 0.397 | 0.110 | 0.267 | 0.057 |
| V ₃ | 0.045 | 0.099 | 0.059 | 0.770 | 0.027 |
| V ₄ | 0.042 | 0.114 | 0.058 | 0.757 | 0.029 |



- Risky
- Distracted
- Aggressive & Risky
- Aggressive
- Aggressive & Distracted

Components V₁, V₃, V₄:

- ≈75% of aggressive trips

Component V₂:

- 17% distracted trips
- 40% risky trips
- 27% of them were clustered as aggressive trips



Conclusions

- Most of the trips (71%) did not have aggressive driving features, such as harsh accelerating and abnormal braking
- Aggressive driving behavior does not necessarily imply risk taking or distracted driving
- Drivers do not have a stable driving profile, but instead they change the way they drive on every trip
- In terms of unsafe driving behavior there are two groups of drivers:
 - those who drive only aggressively
 - those who perform several abnormal behaviors (aggressiveness, speeding, distraction)



Future research steps

- Does an eco driving profile exist?
- Identify additional unsafe behavior while driving (Inappropriate lane changing, Overtaking, Abnormal steering)
- Impact of external factors (traffic, road conditions, adverse weather)
- Causes of distraction: conversations with passengers, listening to music, out of vehicle incidents etc.



NTUA - School of Civil Engineering
Department of Transportation Planning and Engineering

What is your driving identity? Some empirical findings using large-scale smartphone sensors' data

Eleni Mantouka, PhD Candidate



This research is co-financed by Greece and the European Union (European Social Fund- ESF) through the Operational Programme «Human Resources Development, Education and Lifelong Learning» in the context of the project “Strengthening Human Resources Research Potential via Doctorate Research – 2nd Cycle” (MIS-5000432), implemented by the State Scholarships Foundation (IKY).



Operational Programme
Human Resources Development,
Education and Lifelong Learning
Co-financed by Greece and the European Union



Thank you Oseven for providing the data!